Testing Slope Homogeneity in Large Panels

M. Hashem Pesaran and Takashi Yamagata

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Abstract

This paper proposes a modi...ed version of Swamy's test of slope homogeneity for panel data models where the cross section dimension (N) could be large relative to the time series dimension (T). The proposed test exploits the cross section dispersion of individual slopes weighted by their relative precision. In the case of models with strictly exogenous regressors and normally distributed errors, the test is shown to have a standard normal distribution as (N;T) ! 1. Under non-normal errors and in the case of stationary dynamic models, the condition on the relative expansion rates of N and T for the test to be valid is given by N=T ! 0, as $(N;T) !^{j} 1$. Usina Monte Carlo experiments, it is shown that the test has the correct size and satisfactory power in panels with strictly exogenous regressors for various combinations of N and T. For autoregressive (AR) models the proposed test performs well for moderate values of the root of the autoregressive process. But for AR models with roots near unity a biascorrected bootstrapped version of the test is proposed which performs well even if N is large relative to T. The proposed cross section dispersion tests are applied to testing the homogeneity of slopes in autoregressive models of individual earnings using the PSID data. The results show statistically signi...cant evidence of slope heterogeneity in the earnings dynamics, even when individuals with similar educational backgrounds are considered as sub-sets.

JEL-Classi...cation: C12, C33.

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M. Hashem Pesaran Cambridge University & USC Takashi Yamagata Cambridge University

1. Introduction

In many empirical studies, it is assumed that the slope coe Ccients of interest in panel data models are homogeneous across individual units. When the cross section dimension (N) is relatively small and the time series dimension of the panel (T) large, the hypothesis of slope homogeneity can be tested using the SURE (seemingly unrelated regression equation) framework of Zellner (1962). This framework is particularly attractive as it also automatically deals with the possibility of cross section error correlations and dynamics when N is reasonably small (around 5-10) and T suCciently large (around 80-100). However, in many empirical applications N is often (much) larger than T and the SURE approach would not be applicable.

In view of this Pesaran, Smith and Im (1996) proposed the application of the Hausman (1978) testing procedure where the standard ...xed e¤ects estimator is compared to the mean group estimator. However, as will be discussed below, such a procedure is not applicable in the case of panel data models that contain only strictly exogenous regressors and/or in the case of pure autoregressive models.

Recently Phillips and Sul (2003) have also proposed a 'Hausman type' test for slope homogeneity for stationary ...rst-order autoregression (AR(1)) panel data models in presence of cross section dependence, with

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N ...xed as T goes to in...nity. It will be shown below that their testing approach is not valid under cross section independence.

This paper proposes a modi...ed version of the test proposed by Swamy (1970) that applies to panel data models where the cross section dimension could be large relative to the time series dimension. The proposed test is applicable to static as well as to stationary dynamic panel data models, possibly with heteroskedastic errors. In the case of models with strictly exogenous regressors and normally distributed errors, the proposed test is shown to have a standard normal distribution as (N;T) !^j 1, where (N;T) !^j 1 denotes N and T ! 1 jointly. Under non-normal errors and in the case of stationary dynamic models, the condition on the relative expansion rates of N and T for the test to be valid is given by N=T ! 0, as (N;T) !^j 1.

The small sample properties of the proposed test are investigated by means of Monte Carlo experiments. It is shown that the test has satisfactory size and power for T as small as 10 with N as large as 200 in panel data models containing only strictly exogenous regressors, even with non-normal errors. For autoregressive (AR) models the proposed test performs well for moderate values of the root of the AR process under various N and T combinations. But for AR panels with T < N, and roots near unity, a bias-corrected bootstrapped version of the test is proposed which is shown to perform well even if N is large relative to T.

The use of slope homogeneity tests in empirical contexts is illustrated by applying them to testing the homogeneity of slopes in autoregressive models of earnings using the Panel Study of Income Dynamics (PSID) data. The results show evidence of slope heterogeneity in the real earnings dynamics, even when individuals with similar educational backgrounds are considered as sub-sets.

The plan of the paper is as follows. Section 2 sets up the model and reviews existing tests of slope homogeneity. Section 3 considers the asymptotic distribution of alternative dispersion type tests of slope homogeneity and establishes their asymptotic distribution in the context of panel data models where N could be large relative to T. Section 4 considers the application of the proposed ¢ test to stationary dynamic panel data models and develops the biasedcorrected bootstrapped version of the test. Section 5 sets up the Monte Carlo design and summarizes the results. Section 6 discusses the empirical application, and Section 7 provides some concluding remarks.

2. The Model and Existing Tests of Slope Homogeneity

Consider the panel data model with ...xed exects and heterogeneous slopes

$$y_{it} = {}^{\otimes}_{i} + {}^{-i}_{i} x_{it} + {}^{'i}_{it}, i = 1; ...; N, t = 1; ...; T$$
 (2.1)

where \mathbb{B}_i is bounded on a compact set, x_{it} is a k £ 1 vector of regressors, \bar{i}_i is a k £ 1 vector of unknown slope coe \mathcal{C} cients. Stacking the time series observations for i yields

$$y_i = {}^{\otimes}_{i \not i \top} + X_i {}^{-}_i + {}^{'}_{i}, i = 1; 2; ...; N;$$
 (2.2)

where $y_i = (y_{i1}; ...; y_{iT})^0$, z_T is a T £1 vector of ones, $X_i = (x_{i1}; ...; x_{iT})^0$, and "_i = ("_{i1}; ...; "_{iT})⁰. Let

$$Q_{iT} = T^{i} {}^{1} {}^{i} X_{i}^{\emptyset} M_{\dot{c}} X_{i}^{\mathfrak{C}}; *_{iT} = T^{i} {}^{1=2} X_{i}^{\emptyset} M_{\dot{c}}''_{i}; \qquad (2.3)$$

and

where $M_{\dot{c}} = I_T i \dot{c}_T^{i} \dot{c}_T^{\psi_i 1} \dot{c}_T^{\psi_i 1}$, and I_T is an identity matrix of order T.

Consider now the following assumptions:

Assumption 1: "it > IID(0; $\frac{3}{4}i^2$) with 0 < $\frac{3}{4}i^2$ < 1 for all i, and "it and "is are independently distributed for i **6** j and/or t **6** s.

Assumption 2: The k £ k matrices Q_{iT} , i = 1; 2; ...; N, de...ned by (2.3) are positive de...nite, $Q_{iT}^{i}^{1}$ has ...nite second order moments for each i, and Q_{iT} tends to a non-stochastic positive de...nite matrix, Q_{i} , as T ! 1.

Assumption 3: The k £ 1 vectors $*_{iT}$, i = 1; 2; :::; N de...ned by (2.3) are independently distributed across i, and for each i, $*_{iT}$! d N i 0; $^{34}_{i}^{2}$ Q_i, as T ! 1.

Assumption 4: The k £ k pooled observation matrix Q_N de...ned by (2.4) is positive de...nite, and tends to a non-stochastic positive de...nite matrix, Q, as (N;T)!^j 1.²

Assumption 5: $(T_i \ 1) ("_i^{0}M_{i}"_{i})^{i-1}$ has ...nite second order moments for each i.

The null hypothesis of interest is

$$H_0: \bar{i} = \bar{i}$$
 for all $i; k k < K < 1;$ (2.5)

against the alternatives

 $H_1: -i \mathbf{6}$, for a non-zero fraction of slopes.

Assumption 6: Under H_1 , the fraction of slopes that are not the same does not tend to zero as N ! 1.

Remark 1. In the case of randomly distributed slopes, where $\overline{}_i \gg IID(\overline{}; \S^-)$, the null and the alternative hypothesis can be characterized by $H_0: \S^- = 0$, and $H_1: \S^- \in 0$, respectively.

Remark 2. The above assumptions cover both cases of strictly exogenous regressors, as well as when x_{it} contains lagged values of y_{it} .

Remark 3. In the case where the errors, " $_{it}$, are normally distributed Assumption 5 is met if T > 5. See, for example, Smith (1988) for a proof.³

2.1. The Standard F Test

There are a number of procedures that can be used to test H_0 , the most familiar of which is the standard F test de...ned by

$$F = \frac{N(T_i k_i 1)}{k(N_i 1)} \frac{P_{RSSR_i USSR}}{USSR}, \qquad (2.6)$$

 $^{^{2}(}N;T)$!^j denotes joint asymptotics with N and T ! 1 in no particular order.

³Under normality, the rth moment of the inverse of " $_{i}^{0}A$ "_i exits if rank(A) > 2r, where A is a T £ T positive semi-de...nite symmetric matrix.

where RSSR and USSR are restricted and unrestricted residual sum of squares, respectively, obtained under the null ($_i = -$) and the alternative hypotheses. This test is applicable when the regressors are strictly exogenous and the error variances homoskedastic, $\frac{3}{4}_{i}^{2} = \frac{3}{4}^{2}$. But it is likely to perform rather poorly in cases where the regressors might contain lagged values of the dependent variable and/or if the error variances are cross sectionally heteroskedastic.

2.2. Hausman Type Test by Pesaran, Smith and Im

For cases where N > T, Pesaran, Smith and Im (1996) propose using the Hausman (1978) test where the standard ...xed exects (FE) estimator of $^-$,

$$A_{FE} = \begin{pmatrix} \tilde{A}_{i} & I_{i}^{\dagger} \\ \tilde{X}_{i}^{\dagger} M_{\dot{c}} X_{i} & \tilde{X}_{i}^{\dagger} M_{\dot{c}} y_{i}, \\ i=1 & i=1 \end{pmatrix} (2.7)$$

is compared to the mean group (MG) estimator de...ned by

$${}^{\Delta}_{MG} = N^{i} {}^{1} {}^{\Delta}_{i}; \qquad (2.8)$$

where

$${}^{\Delta}{}_{i} = {}^{i} X_{i}^{0} M_{\dot{c}} X_{i}^{{}^{c}}{}_{i}^{1} X_{i}^{0} M_{\dot{c}} y_{i}:$$
 (2.9)

For the Hausman test to have the correct size and be consistent two conditions must be met, however.

(a) Under the null hypothesis, ${}^{\diamond}_{FE}$ and ${}^{\diamond}_{MG}$ must both be consistent, with ${}^{\diamond}_{FE}$ being asymptotically more e¢cient such that

Avar
$$^{a}_{MGi}$$
 $^{a}_{FE} = Avar ^{a}_{MGi}$ Avar $^{a}_{FE} > 0$:

(b) Under the alternative hypothesis [^]_{MG i} [^]_{FE} should tend to a non-zero vector.

In the context of dynamic panel data models with exogenous regressors both of these conditions are met, so long as the exogenous regressors are not drawn from the same distribution, and a Hausman type test based on the di¤erence ${}^{A}_{FE}i {}^{A}_{MG}$ would be valid and is shown to have reasonable small sample properties. See Pesaran, Smith and Im (1996) and Hsiao and Pesaran (2004).

However, there are two major concerns with the routine use of the Hausman procedure as a test of slope homogeneity. It could lack power for certain parameter values, as its implicit null does not necessarily coincide with the null hypothesis of interest. Second, and more importantly, the Hausman test will not be applicable in the case of panel data models containing only strictly exogenous regressors, and/or in the case of pure autoregressive models. In the former case, both estimators, ${}^{A}_{FE}$ and ${}^{A}_{MG}$; are unbiased under the null and the alternative hypotheses and condition (b) will not be satis...ed. Whilst, in the case of pure autoregressive panel data models NT ${}^{A}_{FE}$ i and ${}^{P}_{NT}$ ${}^{A}_{MG}$ i will be asymptotically equivalent and condition (a) will not be met.

2.3. G Test of Phillips and Sul

Phillips and Sul (2003) propose a di¤erent type of Hausman test where instead of comparing two di¤erent pooled estimators of the regression coe Cients (as discussed above), they propose basing the test of slope homogeneity on the di¤erence between the individual estimates and a suitably de...ned pooled estimator. In the context of the panel regression model (2.2), their test statistic can be written as

$$G = {}^{3}_{N i} \dot{z}_{N} - {}^{4}_{pooled} \hat{s}^{i}_{g} {}^{1}_{N i} \dot{z}_{N} - {}^{4}_{pooled};$$

where ${}^{\Delta}_{N} = ({}^{\Delta \emptyset}_{1}; {}^{\Delta \emptyset}_{2}; ...; {}^{\Delta \emptyset}_{N})^{\emptyset}$ is an Nk £ 1 stacked vector of all the N individual estimates, ${}^{\Delta}_{pooled}$ is a suitable pooled estimator of $\bar{}$ (= $\bar{}_{i}$); and $\hat{\$}_{g}$ is a consistent estimator of $\$_{g}$, the asymptotic variance matrix of ${}^{\Delta}_{N}$ i $\dot{\epsilon}_{N}$ - ${}^{\Delta}_{pooled}$, under H₀. Under Assumptions 1-4 and

assuming H₀ holds and N is ...xed, then G $!_d \hat{A}^2_{Nk}$ as T $!_1$; so long as the S_g is a non-stochastic positive de...nite matrix.

As compared to the Hausman test based on ${}^{A}_{MG i}$ ${}^{A}_{FE}$, the G test is likely to be more powerful; but its use will be limited to panel data models where N is small relative to T. Also, the G test will not be valid in the case of pure dynamic models, very much for the same kind of reasons noted above in relation to the Hausman test based on ${}^{A}_{MG i}$ ${}^{A}_{FE}$. This is easily established in the case of the stationary ...rst order autoregressive panel data model considered by Phillips and Sul (2003) where

$$y_{it} = {}^{\otimes}_{i} (1_{i}]_{i}) + {}_{i}y_{it_{i}} 1 + {}^{"}_{it}; j_{i}j < 1;$$

and the aim is to test H_0 : $j_i = j_i$. Phillips and Sul also consider the case where the errors, "it, are cross sectionally dependent through a single factor model. But, given the focus of our analysis, we shall abstract from this problem and continue to assume that "it are cross sectionally independent. Under this set up the appropriate form of the G statistic is given by

$$G = \hat{S}_{N} i \hat{c}_{N} \hat{s}_{pooled} \hat{S}_{g}^{i} \hat{S}_{N} i \hat{c}_{N} \hat{s}_{pooled};$$

where ${}_{,N}^{N} = {}_{,1}^{N} {}_{,2}^{2}$; ...; ${}_{,N}^{N}^{U}$ is the N £ 1 vector of the individual estimates and ${}_{,pooled}^{N}$ is a pooled estimator, such that $({}_{,N}^{U}; {}_{,pooled}^{N})^{U}$ p ${}_{,LN+1}^{N}$ under the null hypothesis. Phillips and Sul consider a number of di¤erent estimators, including Andrew's (1993) median unbiased estimator and its extension to panels. But, as they note, all such estimators yield the same asymptotic covariance matrix as T ! 1. Using the ...xed e¤ects estimator for ${}_{,pooled}^{N}$, and the least squares estimators of ${}_{,i}^{I}$ for ${}_{,i}^{I}$, it is easily veri...ed that under H₀

Avar
$${}^{h}p_{\overline{T}} {}^{3}_{3ii} {}^{r}_{3FE} {}^{i} = Avar {}^{h}p_{\overline{T}} {}^{3}_{3ii} {}^{i}_{3FE} {}^{i}_{3FE} {}^{i}_{3ii} {}^{s}_{3ii} {}^{i}_{3FE} {}^{i}$$

Therefore

$$S_{g} = \frac{\mu_{1_{i}}^{2}}{T} I_{N_{i}} N^{i} N^{i} \partial_{N}^{\dagger};$$

where $Rank(S_g) = N_i$ 1 and S_g is non-invertible.

2.4. Swamy's Test

Swamy (1970) bases his test of slope homogeneity on the dispersion of individual slope estimates from a suitable pooled estimator. Like the F test, Swamy's test is developed for panels where N is small relative to T, but allows for cross section heteroskedasticity. Swamy's statistic applied to the slope coe Ccients can be written as

$$\hat{S} = \frac{\overset{3}{\times} {}^{3}}{{}^{i}i} {}^{i}i {}^{i}WFE \left[\frac{X_{i}^{0}M_{i}X_{i}}{\frac{3}{4}_{i}^{2}} {}^{3}i {}^{i}i {}^{k}WFE \right], \quad (2.10)$$

where

$$\mathcal{M}_{i}^{2} = \frac{\begin{array}{c} 3 \\ y_{i \ i} \\ X_{i}^{2} \\ \hline \\ (T_{i} \\ k_{i} \\ 1) \end{array}}{(T_{i} \\ k_{i} \\ 1)}; \qquad (2.11)$$

and $\ensuremath{^{\circ}_{\sf WFE}}$ is the weighted FE (WFE) pooled estimator of slope coetcients de...ned by

In the case where N is ...xed and T tends to in...nity, under H₀ the Swamy statistic, \hat{S} , is asymptotically chi-square-distributed with k (N i 1) degrees of freedom.⁴

3. Dispersion Type Tests for Large Panels

Our survey of the literature suggests that there are no satisfactory tests of slope homogeneity in panels where N is large relative to T. The standard F test and its extension by Swamy (1970) are appropriate for

⁴See also Hsiao (2003, p.149).

panels where N is small relative to T. Hausman type tests advanced by Pesaran, Smith and Im (1996) apply to large N panels, but are not generally applicable and can sumer from low power. In this paper we propose standardized dispersion statistics that are asymptotically normally distributed as (N;T)!^j 1.

In addition to Swamy's test statistic, \hat{S} , de...ned by (2.10), we also consider the following version

$$S = \frac{\overset{3}{\times} _{i}^{3}}{_{i=1}^{a}} \overset{3}{_{i}} \overset{3}{_$$

where $\frac{3}{4}_{i}^{2}$ is an estimator of $\frac{3}{4}_{i}^{2}$ based on 4 _{FE}, namely

$$\mathcal{H}_{i}^{2} = \frac{\begin{array}{c} 3 \\ y_{i \, i} \\ X_{i}^{2} \\ \hline \\ T_{i \, 1} \end{array}}{\begin{array}{c} 3 \\ M_{i} \\ Y_{i \, i} \\ Y_{i \, i} \\ X_{i}^{2} \\ FE \\ \hline \\ \end{array}}, \qquad (3.2)$$

and \tilde{W}_{WFE} is the weighted FE estimator also computed using $\frac{3}{4}_{i}^{2}$, namely $\tilde{\mathbf{x}}$

$$\tilde{W}_{FE} = \overset{\mathbf{A}}{\underset{i=1}{\overset{\times}{_{i=1}}}} \frac{X_{i}^{0} M_{i} X_{i}}{\overset{\times}{_{i=1}^{34}}} \overset{i \ i \ 1}{\overset{\times}{_{i=1}}} \overset{\mathbf{X}}{\underset{i=1}{\overset{\times}{_{i=1}}}} \frac{X_{i}^{0} M_{i} y_{i}}{\overset{\times}{_{i=1}^{34}}} :$$
(3.3)

Although the dimerence between \$ and \$ might appear slight at ...rst, the choice of the estimator of $\frac{3}{4}i^2$ has important implications for the properties of the two dispersion tests as N and T tends to in...nity.

To establish the asymptotic results for the Swamy's version of the dispersion test we need the following more restrictive version of Assumption 5:

Assumption 5⁰: $\frac{3}{4}$ is a consistent estimator of $\frac{3}{4}$ such that

$$\frac{\frac{34^{2}}{i}}{\frac{34^{2}}{i}} = 1 + O_{p}^{i} T_{i}^{1} {}^{\ddagger}; \qquad (3.4)$$

and $E^{i} 1 = \mathcal{X}_{i}^{2}$ exists and is bounded.

We also note that under Assumptions 1-4

$$*_{iT}^{0} Q_{iT}^{i} *_{iT} = O_{p}(1); N^{i} *_{i=1}^{N} *_{i=1}^{3/4} Q_{iT} = Q_{N} = O_{p}(1);$$
 (3.5)

and

$$\mathbf{\tilde{A}}$$
 $\mathbf{\tilde{A}}$ $\mathbf{\tilde{A}}$

Consider …rst the Swamy's version of the dispersion test. Under H_0 we have

$${}^{3} \overset{\circ}{_{i}i} \overset{\circ}{_{WFE}} = T^{i} {}^{1=2}Q^{i}_{iT} {}^{1} {}^{*}_{iT} i T^{i} {}^{1=2}N^{i} {}^{1=2} N^{i} {}^{1=2} N^{i} {}^{1}_{i} {}^{2}Q_{iT} N^{i} {}^{1=2} \overset{\mathcal{M}}{_{i=1}} \overset{\mathcal$$

where Q_{iT} and \ast_{iT} are given by (2.3). Using this result in (2.10) it is easily seen that

$$p_{\overline{N}}^{1} \hat{S} = p_{\overline{N}}^{1} \frac{\aleph}{i=1}^{n} \frac{\aleph_{iT}^{0} Q_{iT}^{1} N_{iT}}{N_{i}^{2}} i p_{\overline{N}}^{1} \frac{p_{\overline{N}}^{1} \tilde{A}_{i}^{2} N_{iT}}{p_{\overline{N}}^{2}} \frac{P_{N}^{1} \tilde{A}_{i}^{2} N_{iT}}{N} \frac{P_{N}^{1} \tilde{A}_{i}^{2} N_{i}^{2} N_{i}}{N} \frac{P_{N}^{1} \tilde{A}_{i}^{2} N_{i}^{2} N_{i}}{N} \frac{P_{N}^{1} \tilde{A}_{i}^{2} N_{i}^{2} N_{i}}{N} \frac{P_{N}^{1} \tilde{A}_{i}^{2} N_{i}^{2} N_{i}}{N} \frac{P_{N}^{1} \tilde{A}_{i}^{2} N_{i}}{N} \frac{P_{N}^{1} \tilde{A}_{i}^{2}$$

In view of (3.5) and (3.6) and using (3.4) we have,

$$N^{i} \stackrel{1=2}{\overset{N}{_{i=1}}} \stackrel{N}{\overset{N}{_{i}}} \stackrel{2}{\overset{N}{_{iT}}} \stackrel{0}{\overset{Q}{_{iT}}} \stackrel{1}{\overset{N}{_{iT}}} = N^{i} \stackrel{1=2}{\overset{N}{_{i=1}}} \stackrel{N}{\overset{N}{_{iT}}} \stackrel{0}{\overset{N}{_{iT}}} \stackrel{1}{\overset{Q}{_{iT}}} \stackrel{1}{\overset{N}{_{iT}}} \stackrel{1}{\overset{N}{_{iT}}} + O_{p} \stackrel{\overline{N}}{\overset{N}{_{T}}} \stackrel{1}{\overset{N}{_{iT}}} ;$$

$$N^{i} \stackrel{1=2}{\overset{N}{_{i=1}}} \stackrel{N}{\overset{N}{_{i}}} \stackrel{2}{\overset{N}{_{iT}}} = N^{i} \stackrel{1=2}{\overset{N}{_{i=1}}} \stackrel{N}{\overset{N}{_{iT}}} \stackrel{2}{\overset{N}{_{iT}}} \stackrel{N}{\overset{N}{_{iT}}} + O_{p} \stackrel{\overline{N}}{\overset{N}{_{T}}} \stackrel{1}{\overset{N}{_{iT}}} ;$$

and

$$N^{i} \stackrel{1}{\overset{N}{_{i=1}}} \stackrel{1}{\overset{N}{_{i}}} \stackrel{2}{_{i}} O_{iT} = N^{i} \stackrel{1}{\overset{N}{_{i=1}}} \stackrel{1}{\overset{N}{_{i}}} \stackrel{2}{_{i}} O_{iT} + O_{p} \stackrel{1}{\overset{1}{_{T}}} \stackrel{1}{\overset{1}}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}}} \stackrel{1}{\overset{1}} \stackrel{1}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}} \stackrel{1}{\overset{1}} \stackrel{$$

Hence (again using (3.5) and (3.6))

or equivalently

$$N^{i} {}^{1=2} \hat{S} = N^{i} {}^{1=2} \frac{ \varkappa}{i} \frac{\mu_{i} \mu_{i}}{M_{i}^{2}} + O_{p} \frac{\tilde{A}_{p} \mu_{i}}{T} + O_{p} \frac{\mu_{i}}{P_{i}} + O_{p} \frac{1}{P_{i}} ; \quad (3.8)$$

where

$$\mathsf{P}_{i} = \mathsf{M}_{\dot{c}} \mathsf{X}_{i}^{i} \mathsf{X}_{i}^{\emptyset} \mathsf{M}_{\dot{c}} \mathsf{X}_{i}^{\sharp} \mathsf{X}_{i}^{0} \mathsf{M}_{\dot{c}}$$
(3.9)

Consider now our modi...ed version of Swamy's statistic, S, which under H_0 can be similarly written as

$$\frac{1}{N}S = P \frac{1}{N} \frac{\aleph}{i=1} \frac{\aleph}{\frac{1}{N}} \frac{\aleph_{iT}^{0} Q_{iT}^{1} N_{iT}}{\frac{3}{4}_{i}^{2}} i P \frac{1}{N} \frac{\tilde{A}_{P_{N}} N}{\frac{1}{N}} \frac{\frac{1}{N} \frac{1}{N} \frac{\tilde{A}_{P_{N}} N}{\frac{1}{N}} \frac{\frac{1}{N} \frac{1}{N} \frac{\tilde{A}_{P_{N}} N}{\frac{1}{N} \frac{1}{N} \frac{1}{N} \frac{\tilde{A}_{P_{N}} N}{\frac{1}{N} \frac{1}{N} \frac{1}{N} \frac{1}{N} \frac{\tilde{A}_{P_{N}} N}{\frac{1}{N} \frac{1}{N} \frac{1}{N} \frac{1}{N} \frac{\tilde{A}_{P_{N}} N}{\frac{1}{N} \frac{1}{N} \frac{1}{$$

Using (3.2) ...rst note that after some algebra under H₀ we have

$$(T \ i \ 1)_{i}^{3}_{i}^{2} = "_{i}^{0}M_{i}"_{i} \ i \ 2N^{i} \ {}^{1=2}_{N} N^{\alpha} Q_{N}^{\alpha} \ {}^{1}_{N} + N^{i} \ {}^{1}_{N} N^{\alpha} Q_{N}^{\alpha} \ {}^{1}_{O} Q_{N}^{\alpha} \ {}^{1}_{O} Q_{N}^{\alpha} \ {}^{1}_{O} Q_{N}^{\alpha} \ {}^{1}_{N} N^{\alpha} C_{N}^{\alpha} \ {}^{1}_{O} Q_{N}^{\alpha} \ {}^{1}_{O} Q_{N}^{\alpha} \ {}^{1}_{O} N^{\alpha}$$

where

$$Q_{N}^{\alpha} = N^{i} {}^{1} \sum_{i=1}^{M} Q_{iT}; \ w_{N}^{\alpha} = N^{i} {}^{1=2} \sum_{i=1}^{M} w_{iT};$$

But using results in (3.5) and (3.6) and recalling that $0< {}^3\!\!4_i^2<1$, we also $have^5$

$$Q_N^{\alpha} = O_p(1); \ N_N^{\alpha} = O_p(1):$$

Therefore,

It is also clear from (3.11) that for N su¢ciently large $\frac{3}{4}$ ² has second order moments for any T so long as Assumption 5 is satis...ed. Therefore, under Assumptions 2 and 3 the second order moments of $\frac{3}{4}$ ² $_{iT}$ and $\frac{3}{4}$ ² $_{iT}$ will exist for N large and we have

$$N^{i} \stackrel{1=2}{\stackrel{}{\overset{}}} \underset{i=1}{\overset{}{\overset{}}} {\overset{}{\overset{}}}_{iT} Q^{i}_{iT} \stackrel{1}{\overset{}}_{iT} = N^{i} \stackrel{1=2}{\overset{}{\overset{}}} \overset{\overset{}{\overset{}}}{\overset{}{\overset{}}} \stackrel{\overset{}{\overset{}}}{\overset{}{\overset{}}} \frac{\overset{}{\overset{}}}{\overset{}} \stackrel{\overset{}{\overset{}}}{\overset{}}}{\overset{}{\overset{}}} \stackrel{\overset{}{\overset{}}}{\overset{}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}} \stackrel{\overset{}}{\overset{}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}} \stackrel{1}{\overset{}} \overset{1}{\overset{}} \stackrel{1}{\overset{}} \overset{1}}{\overset{}} \overset{1}{\overset{}}} \overset{1}{\overset{}} \overset{1}{\overset{}}} \overset{1}{\overset{}} \overset{1}{\overset{}}} \overset{1}{\overset{}} \overset{1}}{\overset{}} \overset{1}{\overset{}} \overset{1}{\overset{}}} \overset{1}{\overset{}} \overset{1}{\overset{}} \overset{1}{\overset{}}} \overset{1}{\overset{}} \overset{1}{\overset{}} \overset{1}{\overset{}}} \overset{1}{\overset{}} \overset{1}}{\overset{}} \overset{}}{\overset{}}} \overset{1}{\overset{}} \overset{1}}{\overset{}} \overset{}}{\overset{}} \overset{1}{\overset{}} \overset{1}{$$

$$N^{i} \stackrel{1=2}{\overset{\mathcal{H}}{=}} \stackrel{\mathcal{H}}{\overset{3}_{i}} \stackrel{2}{\overset{}{}} _{iT} = N^{i} \stackrel{1=2}{\overset{1=2}{\overset{\mathcal{H}}{=}}} \stackrel{\mathcal{H}}{\overset{1}{\overset{}{=}} \stackrel{1}{\overset{1}{\overset{}}} \stackrel{\mathcal{H}}{\overset{1}{\overset{}{=}} \stackrel{1}{\overset{1}{\overset{}}} \stackrel{1}{\overset{1}{\overset{}}} \stackrel{1}{\overset{1}{\overset{}}} \stackrel{N_{i}}{\overset{1}{\overset{}}} \stackrel{1}{\overset{1}{\overset{}}} \stackrel{N_{i}}{\overset{1}{\overset{}}} \stackrel{1}{\overset{1}{\overset{}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{}}} \stackrel{1}{\overset{1}{\overset{1}{\overset{}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{}}} \stackrel{1}{\overset{1}{\overset{1}{\overset{}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}}} \stackrel{1}{\overset{1}{\overset{1}{\overset{1}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}{\overset{1}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}{\overset{1}}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}}} \stackrel{N_{i}}{\overset{1}{\overset{1}}} \stackrel{N_{i}}{\overset{1}}} \stackrel{N_{i}}{\overset{1}{\overset{1}{\overset{1}}{\overset{1}}}} \stackrel{N_{i}}{\overset{1}{\overset{1}}} \stackrel{N_{i}}{\overset{1}}} \stackrel{N_{i}}{\overset{1}} \stackrel{N_{i}}{\overset{1}}} \stackrel{N_{i}}{\overset{1}} \stackrel{N_{i}}{\overset{1}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{I}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{I}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}}{\overset{N_{i}}} \stackrel{N_{i}}}{\overset{N_{i}}} \stackrel{N_{i}}{\overset{N_{i}}} \stackrel{N_{i}}}{\overset{N_{i}}} \stackrel{N_{i}}} \stackrel{N_{i}}} \stackrel{N_{i}}} \stackrel{N_{i}}}{\overset{N_{i}}} \stackrel{N_{i}}}{\overset{N$$

⁵Note that by assumption Q_{iT} and \mathbf{w}_{iT} have ...nite second order moments.

and

$$N^{i} \stackrel{1}{\overset{3}{_{i}}} \stackrel{3}{_{i}} \stackrel{1}{_{i}} \stackrel{2}{_{i}} O_{iT} = N^{i} \stackrel{1}{\overset{3}{_{i}}} \stackrel{1}{\overset{3}{_{i}}} \stackrel{1}{\overset{3}{_{i}}} \stackrel{1}{\overset{3}{_{i}}} \stackrel{1}{\underset{i=1}{\overset{3}{_{i}}} \stackrel{1}{\overset{3}{_{i}}} \stackrel{1}{\underset{i=1}{\overset{3}{_{i}}} \stackrel{1}{\underset{i=1}{\overset{1}{\underset{i=1}{\overset{1}{\underset{i=1}{\underset{i=1}{\overset{1}{\underset{i=1}{\overset{1}{\underset{i=1}{\underset{i=1}{\overset{i=1}{\underset{i=1}{\overset{i=1}{\underset{i=1}{\overset{1}{\underset{i=1}{\underset{i=1}{\overset{i=1}{\underset{i=1}$$

Using these results in (3.10)

$$N^{i}^{1=2}S = N^{i}^{1=2} \underbrace{\overset{\overset{\overset{\overset{}}}{\times}}{\overset{\overset{\overset{}}{\to}}{\overset{\overset{}}{\to}}} \overset{\overset{\overset{\overset{}}{\to}}{\overset{\overset{}}{\to}} \overset{\overset{\overset{}}{\to}}{\overset{\overset{}}{\to}} \overset{\overset{\overset{}}{\to}}{\overset{\overset{}}{\to}} \overset{\overset{\overset{}}{\to}}{\overset{\overset{}}{\to}} \overset{\overset{\overset{}}{\to}}{\overset{\overset{}}{\to}} \overset{\overset{\overset{}}{\to}}{\overset{\overset{}}{\to}} \overset{\overset{}}{\to} \overset{\overset{\overset{}}{\to}}{\overset{\overset{}}{\to}} \overset{\overset{}}{\to} \overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{}}{\to} \overset{\overset{}}{\to} \overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{\overset{}}{\to} \overset{}}{\to} \overset{\overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{\overset{}}{\to} \overset{}}{\to} \overset{\overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{\overset{}}{\to} \overset{}}{\to} \overset{\overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}{\to} \overset{}}$$

or equivalently, since $*_{iT}^{0} Q_{iT}^{i} *_{iT} = "_{i}^{0} P_{i}"_{i}$,

$$N^{i} {}^{1=2}S = N^{i} {}^{1=2} \bigotimes_{i=1}^{k} z_{i} + O_{p} {}^{i}T^{i} {}^{1} + O_{p} {}^{k}N^{i} {}^{1=2}; \quad (3.12)$$

where

$$z_{i} = \frac{\mu_{i} M_{i} \eta_{i}}{T_{i} 1} \eta_{i}^{1}$$
(3.13)

A comparison of (3.8) and (3.12) clearly shows that for N and T large the S version of the dispersion test could be preferable to the S version since the latter requires N and T to increase at the same rates whilst the former does not necessarily require this condition. In fact, as we shall see below, in the case of strictly exogenous regressors the slope homogeneity test based on S would be valid for (N;T) !^j 1, whilst a test based on S, in addition to (N;T) !^j 1 would also require that N=T! 0. In the case of dynamic panels both versions of the dispersion test require the additional condition N=T! 0, and a biascorrected bootstrapped test will be considered.

Before proceeding further we summarize the above results in the following theorem.

Theorem 3.1. Consider the panel data model (2.1), and suppose that Assumptions 1-5 hold. Then the dispersion statistics \hat{S} and \hat{S} de...ned by (2.10) and (3.1), respectively, can be written as

$$N^{i} {}^{1=2}S = N^{i} {}^{1=2} \bigotimes_{i=1}^{k} z_{i} + O_{p} {}^{i}T^{i} {}^{1} + O_{p} {}^{3}N^{i} {}^{1=2}; \quad (3.15)$$

where P_i and z_i are de...ned by (3.9) and (3.13), respectively.

This theorem is fairly general and applies irrespective of whether the regressors are strictly exogenous or contain lagged dependent variables, and holds for non-normal errors.

Consider now the case where the regressors are strictly exogenous and the errors are normally distributed, " $_i \gg IIDN \ 0; \frac{3}{4}_i^2 I_T$. In this case $\frac{3}{4}i^{2}"_{i}^{0}P_{i}"_{i}$ has a chi-square distribution with k degrees of freedom and the following standardized version of \hat{S} could be used when N and T are both large \tilde{A}

$$\hat{c} = \frac{P_{-}}{N} \frac{N^{i} \hat{s}_{i} k}{2k} : \qquad (3.16)$$

Using (3.14) it is easily seen that

$$\hat{\mathbf{C}} = \mathbf{N}^{i} {}^{1=2} \frac{\mathbf{X}}{i=1} \frac{\mathbf{A}_{i}^{j} {}^{2} {}^{**} {}^{0} \mathbf{P}_{i} {}^{*} {}^{i} {}^{i} \mathbf{R}}{2k} + \mathbf{O}_{p} {}^{*} \mathbf{N}^{1=2} \mathbf{T}^{i} {}^{1} + \mathbf{O}_{p} {}^{*} \mathbf{N}^{i} {}^{1=2} ;$$

and under H₀, $\hat{\mathbb{C}}$! d N(0; 1) as (N; T) ! 1 such that $\overline{\mathbb{N}}=T$! 0.

Turning to the S version of the test, using well known results in von Neumann (1941) on moments of the ratio of quadratic forms in standard normal variates, we ...rst note that

$$E(z_i) = \frac{E("_i^{\emptyset}P_i"_i)}{E^{i}"_i^{\emptyset}M_{\dot{c}}"_i = (T_i \ 1)} = \frac{(T_i \ 1)tr(P_i)}{tr(M_{\dot{c}})} = k_i$$

and

$$E^{i}z_{i}^{2^{c}} = \frac{E("_{i}^{0}P_{i}"_{i}"_{i}^{0}P_{i}"_{i})}{E^{i}"_{i}^{0}M_{i}"_{i}"_{i}^{0}M_{i}"_{i}} = (T_{i} 1)^{2} = \frac{\mu_{T_{i}}}{T_{i} 1} (T_{i} 1)^{2} = \mu_{T_{i}}^{1} (T_$$

so that

var (z_i) = v²(T; k) =
$$\frac{2k(T_i 1)i 2k^2}{T+1}$$
. (3.17)

These results, therefore, motivate the following standardized version of the S statistic \tilde{A} !

$$\mathbf{c} = \frac{\mathbf{p}_{\mathbf{N}}}{\mathbf{N}} \frac{\mathbf{N}^{i} \, {}^{1}\mathbf{S}_{i} \, \mathbf{k}}{\mathbf{v}(\mathsf{T};\mathsf{k})} ; \qquad (3.18)$$

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which in view of (3.15) can also be written as

$$\mathbf{c} = \mathbf{p}_{\overline{N}}^{1} \mathbf{N}_{i=1}^{\mathbf{k}} \mathbf{P}_{\mathbf{i}}^{\mathbf{z}_{i}} \mathbf{N}_{i}^{\mathbf{q}} + \mathbf{O}_{p}^{\mathbf{i}} \mathbf{T}_{i}^{\mathbf{i}} \mathbf{P}_{\mathbf{i}}^{\mathbf{q}} + \mathbf{O}_{p}^{\mathbf{i}} \mathbf{N}_{i}^{\mathbf{i}} \mathbf{P}_{\mathbf{i}}^{\mathbf{q}} + \mathbf{O}_{p}^{\mathbf{i}} \mathbf{N}_{i}^{\mathbf{i}} \mathbf{P}_{\mathbf{i}}^{\mathbf{q}} + \mathbf{O}_{p}^{\mathbf{i}} \mathbf{N}_{i}^{\mathbf{q}} \mathbf{P}_{\mathbf{i}}^{\mathbf{q}} + \mathbf{O}_{p}^{\mathbf{i}} \mathbf{N}_{i}^{\mathbf{q}} \mathbf{P}_{\mathbf{i}}^{\mathbf{q}} + \mathbf{O}_{p}^{\mathbf{i}} \mathbf{N}_{i}^{\mathbf{q}} \mathbf{P}_{\mathbf{i}}^{\mathbf{q}} \mathbf{P}_{\mathbf{i}}^$$

Since $(z_{i \mid i} \mid k) = v(T; k) \gg IID(0; 1)$, using standard central limit theorems it follows that under H₀, $\pounds \mid_d N(0; 1)$ as $(N; T) \mid_{j}^{j} 1$. The following theorem provides a formal statement of these results.

Theorem 3.2. Consider the panel data model (2.1), suppose that the k £ 1 regressors x_{it} are strictly exogenous, "_i » IIDN $0;_{i}^{2}I_{T}$, and Assumptions 1-5 hold. Then under H₀

$$\hat{C} = \frac{1}{d} N(0;1);$$
 as $(N;T) \stackrel{j}{=} 1;$ such that $N = T = 0;$

and

¢! d N (0; 1); as (N;T)!^j 1;

where the standardized dispersion statistics, \hat{C} and \hat{C} are de...ned by (3.16) and (3.18), respectively.

Under strictly exogenous regressors and normal errors the null distribution of the ¢ statistic does not depend on the relative expansion rates of N and T, whilst the same is not true of the Swamy version of the test. The di¤erences between the two versions are, however, less clear cut as the exogeniety and the normality assumptions are relaxed. For example, if the normality assumption is relaxed, to eliminate the dependence of ¢ on the higher order moments of "it, we also need \overline{N} =T ! 0, as (N;T) ! 1. This result is summarized in the following corollary to Theorem 3.2.

Corollary 3.3. Suppose that the conditions of Theorem 3.2 are met, but the errors, "it; are not necessarily normally distributed. Instead assume that they are independently distributed over i and t and have ...-nite fourth order moments. Then as (N;T) ^j 1; N N^{i 1}S_i k ! d N(0;var(z_i)); if it is also required that N=T ! 0, as (N;T) ^j 1. The ...nite T expression for var(z_i) in the case of non-normal errors would be rather complicated to obtain, but the result in (3.17) derived for the normal error case is likely to provide a reasonable approximation in practice.

See Appendix A.1 for a proof.

Remark 4. The proposed testing approach can be readily extended to testing the homogeneity of a sub-set of slope coe Ccients. Consider the following partitioned form of (2.1):

$$y_{i} = {}^{\text{\tiny (B)}}_{\text{\tiny T} \pm 1} + X_{i1} {}^{\text{\tiny (i)}}_{\text{\tiny T} \pm k_{1}} + X_{i2} {}^{\text{\tiny (i)}}_{\text{\tiny T} \pm k_{2}} + {}^{\text{\tiny (i)}}_{\text{\tiny (i)}}, i = 1; 2; ::; N;$$

or

$$y_{i} = X_{i1}^{*} \mu_{i} + X_{i2}^{*} \mu_{i} + X_{i2}^{*}$$

where $X_{i1}^{x} = (z_T; X_{i1})$ and $\mu_i = {}^{i} {}^{\mathbb{R}}_{i}; {}^{-0} {}^{\mathbb{C}}_{i1}$. Suppose the slope homogeneity hypothesis of interest is given by

$$H_0: \ _{i2} = \ _2, \text{ for } i = 1; 2; ...; N:$$
 (3.19)

Our version of the dispersion test statistic in this case is given by

$$S_{2} = \frac{\overset{3}{\overset{}}}{\underset{i=1}{\overset{}}}{}^{a}_{i2 \ i} \ \overset{=}{\underset{2;WFE}{\overset{}}}{}^{(i)} \frac{X_{i2}^{0}M_{i1}^{\pi}X_{i2}}{\overset{3}{\underset{i}{\overset{}}}{}^{a}_{i2 \ i}} \overset{3}{\underset{2;WFE}{\overset{}}}{}^{(i)}_{i1} \frac{X_{i2}}{\overset{3}{\underset{i}{\overset{}}}{}^{a}_{i2 \ i}} \overset{3}{\underset{2;WFE}{\overset{}}},$$

where

$$\hat{\mathbf{A}}_{i2} = \hat{\mathbf{i}} \times_{i2}^{\emptyset} M_{i1}^{\pi} \times_{i2}^{\Psi_{i}} \hat{\mathbf{i}}^{1} \times_{i2}^{\emptyset} M_{i1}^{\pi} y_{i}.$$

$$\hat{\mathbf{A}}_{i2} \times \frac{\mathbf{A}_{i2}^{\emptyset} M_{i1}^{\pi} \times_{i2}}{\frac{34_{i}^{2}}{34_{i}^{2}}} \hat{\mathbf{i}}^{1} \times \frac{\mathbf{A}_{i2}^{\emptyset} M_{i1}^{\pi} y_{i}}{\frac{1}{34_{i}^{2}}}$$

$$\mathcal{M}_{i1}^{\pi} = I_{T \ i} X_{i1}^{\pi} X_{i1}^{\pi} X_{i1}^{\pi} X_{i1}^{\pi} X_{i1}^{\pi} X_{i1}^{\pi} X_{i1}^{\pi},$$

$$\mathcal{M}_{i1}^{2} = \frac{y_{i \ i} X_{i2}^{2} Y_{2;FE} M_{i1}^{\pi} Y_{i1} X_{i2}^{2} Y_{2;FE}}{T_{i \ i} K_{1 \ i} 1};$$

and

$${}^{A}_{2;FE} = \overset{\widetilde{A}}{\underset{i=1}{\times}} X_{i2}^{\emptyset} M_{i1}^{x} X_{i2} \overset{I}{\underset{i=1}{\times}} X_{i2}^{\emptyset} M_{i1}^{x} y_{i}.$$

Using a similar line of reasoning as above, it is now easily seen that under H_0 de...ned by (3.19)

$$c_2 = \frac{P_{-N}}{N} \frac{N^{i} {}^{1}S_{2} {}_{i} {}^{k_2}}{v(T; k_1; k_2)} !_{d} N(0; 1); \text{ as } (N; T) !^{j} 1;$$

where

$$v^{2}(T; k_{1}; k_{2}) = \frac{2k_{2}(T | k_{1} | 1) | 2k_{2}^{2}}{T | k_{1} + 1}$$

Remark 5. The proposed slope homogeneity tests can also be extended to unbalanced panels. Denoting the number of time series observations on the i^{th} cross section by T_i , our version of the standardized dispersion statistic is given by

$$\mathbf{c} = \mathbf{p}_{\overline{\mathbf{N}}}^{1} \frac{\mathbf{\tilde{A}} \quad \mathbf{i}}{\sum_{i=1}^{N} \frac{\mathbf{d}_{i i} \quad \mathbf{k}}{\mathbf{v}(\mathsf{T}_{i}; \mathbf{k})}}; \qquad (3.20)$$

where

$$v^{2}(T_{i};k) = \frac{2k(T_{i}|i|) + 2k^{2}}{T_{i} + 1};$$

$$d_{i} = \int_{i}^{3} \int_{i}^{4} \frac{\sqrt{2}}{WFE} \int_{i}^{3} \frac{X_{i}^{0}M_{i}X_{i}}{\frac{3}{4}_{i}^{2}} \int_{i}^{3} \int_{i}^{4} \frac{1}{VFE} \int_{i}^{4} \frac{X_{i}^{0}}{WFE} \int_{i}^{3} \frac{X_{i}^{$$

$$\begin{split} X_i &= (x_{i1}; x_{i2}; :::; x_{iT_i}), \ M_{\dot{c}i} &= I_{T_i \ i} \ \dot{c}_{T_i} \ \dot{c}_{T_i} \ \dot{c}_{T_i} \ \dot{c}_{T_i} \ \text{with} \ \dot{c}_{T_i} \ \text{being} \\ a \ T_i \ \pounds \ 1 \ \text{vector of unity,} \end{split}$$

$${}^{\Delta}{}_{i} = {}^{i} X_{i}^{\emptyset} M_{\dot{z}i} X_{i}^{{}^{\varphi}{}_{i} 1} X_{i}^{\emptyset} M_{\dot{z}i} y_{i}; \qquad (3.21)$$

$$\tilde{W}_{\text{WFE}} = \frac{\tilde{A}_{\text{WFE}}}{\sum_{i=1}^{i} \frac{X_{i}^{0} M_{i}X_{i}}{\frac{34_{i}^{2}}{3}}}{\sum_{i=1}^{i} \frac{X_{i}^{0} M_{i}Y_{i}}{\sum_{i=1}^{i} \frac{X_{i}^{0} M_{i}Y_{i}}{\frac{34_{i}^{2}}{3}}}; \quad (3.22)$$

$$y_{i} = (y_{i1}; y_{i2}; ...; y_{iT_{i}})^{0}$$

$$3_{i}^{2} = \frac{y_{i i} X_{i}^{a} F_{E} M_{i i} X_{i}^{a} F_{E}}{T_{i i} 1};$$

and

$${}^{\Delta}_{FE} = { \begin{array}{*{20}c} \tilde{A} & {}^{I}_{i} {}^{i} {}^{1} \\ X_{i}^{0} M_{\dot{c}i} X_{i} & {}^{I}_{i} M_{\dot{c}i} y_{i} \\ i = 1 & i = 1 \end{array} X_{i}^{0} M_{\dot{c}i} y_{i} : \qquad (3.23)$$

An extension to testing the homogeneity of a sub-set of slope coe Ccientsin the case of the unbalanced panels is straightforward and is easily derived using the result in Remark 4.

3.1. Asymptotic Local Power of the ¢ Test

For the analysis of the asymptotic power of the $\ensuremath{\mathbb{C}}$ test, we adopt the following local alternatives^6

$$H_{1;NT} : \bar{i} = \bar{i} + \frac{\pm i}{N^{1=4}T^{1=2}}; \quad i = 1; 2; ...; N; \quad (3.24)$$

where \pm_i , i = 1; 2; ...; N are k ± 1 vectors of ...xed constants. As we shall with N ! 1, it is not necessary that \pm_i are non-zero for all i.

Under the above local alternatives and assuming that the regressors are strictly exogenous we have⁷

$$\mathbf{C} = \mathbf{P} \frac{1}{\overline{N}} \mathbf{N}_{i=1}^{\mathbf{X}} \mathbf{P} \frac{\mathbf{Z}_{i i} \mathbf{k}}{\mathbf{v}(T; \mathbf{k})} \mathbf{P} + \frac{\tilde{A}_{NT}}{\mathbf{v}(T; \mathbf{k})} + O_p \mathbf{N}_{i}^{i 1=4} + O_p \mathbf{i}_{T_i}^{i 1^{\mathbf{C}}};$$

where

⁶Similar results also hold for the \hat{C} version of the test.

⁷ For a proof see Appendix A.2.

Hence, it readily follows that under $H_{1:NT}$

where

$$\tilde{A} = \lim_{N! = 1}^{N} \frac{\$}{N} \sum_{i=1}^{N} \frac{\$}{N} \sum_{i=1}^{N} \frac{1}{N} \sum_{i=1}^{N} \frac{\$}{N} \sum_{i=1}^{N} \sum_{i=1}^{N} \frac{\$}{N} \sum_{i=1}^{N} \sum_{i=1}^{N$$

Recall that $Q_i = p \lim_{T_{i=1}} {}^{i} T_i {}^{1}X_i^{0}M_i X_i^{c}$. The ¢ test has power against local alternatives if $\tilde{A} > 0$. Since Q_i is a symmetric positive de...nite matrix, using the the Cholesky decomposition, $Q_i = C_i^{0}C_i$, and setting $\Xi_i = C_i \pm_i = \frac{3}{4}$; and $W_i = \frac{3}{4} {}^{1}C_i$ we have

$$\tilde{A} = \lim_{N!=1}^{8} \left\{ \begin{array}{c} \tilde{A} \\ \tilde{N} \\$$

where $M_w = I_{T\,i} W (W^0 W)^{i\ 1} W$. Hence, $\tilde{A} \ 0$, and in general the ¢ test is asymptotically powerful if $\pm_i 6$ 0 for a non-zero fraction of the cross section units in the limit, as speci...ed under Assumption 6. Such an alternative, for example, allows a sub-set of the slope coe¢cients and/or a sub-set of cross section units to be homogeneous.

The above result also suggests that the power of the C test is likely to increase faster with T than with N.

4. Testing Slope Homogeneity in Autoregressive Models

Consider the stationary pth order autoregressive (AR(p)) processes

$$y_{it} = {}^{\mathbb{R}}_{i} + \sum_{j=1}^{*} {}^{ij} y_{i;t_{j}} + {}^{"it,}$$
 (4.1)

 $\mathbf{\hat{p}}_{j=1}^{p}$; $ij x^{j}$, k^{f} all outside the unit circle, and assume that "it "IDN" 0; $\frac{3}{4}_{i}^{2}$. Testing the homogeneity of the slopes

$$H_0: \ _{ij} = _{j} \text{ for all } i = 1; 2; ...; N \text{ and } j = 1; 2; ...; p;$$
 (4.2)

can be carried out as computing the dispersion statistic, (3.1), with

$$\begin{array}{rcl} X_{i} & = & (y_{i;i-1};y_{i;i-2};...;y_{i;i-p}); \\ y_{i;i-j} & = & (y_{i;i-j+1};y_{i;i-j+2};....;y_{i;T_{i-j-j}})^{0}; \; j \; = \; 1;2;...; p: \\ \end{array}$$

Using standard results from the literature of stationary autoregressive processes, it is easily established that Assumptions 1-5 are satis...ed in the case of stationary autoregressive processes, and as a result Theorem 3.1 continues to hold in this case as well. In particular we have

$$N^{i} {}^{1=2}S = \frac{1}{N} \sum_{i=1}^{N} z_i + O_p {}^{i}T^{i} {}^{1} + O_p {}^{i}N^{i} {}^{1=2}; \qquad (4.3)$$

where z_i is de...ned by (3.13), with $X_i = (y_{i;i}; y_{i;j}; y_{i;j})$. However, in the case of AR processes exact expressions for the mean and variance of z_i are not easy to derive, and more importantly such exact results would in general depend on the unknown autoregressive coe¢cients, _ij, which further complicates any test that is directly based on the Swamy statistic, S. To deal with this problem we explore two alternative approaches. (i) An asymptotic procedure where $E(z_i)$ and $V ar(z_i)$ are approximated by terms of up to order T i = (i). A bootstrap approach where the small sample dependence of $E(z_i)$ and $V ar(z_i)$ on $_{i} = (_{i1}; _{i2}; ...; _{ip})^0$ is taken into account using resampling techniques based on bias-corrected estimates of $_{i}^{\wedge}$.

4.1. An Asymptotic ¢ Test for AR(p) Panel Data Models

In the case of dynamic models the two versions of the dispersion tests, $\hat{\mathbb{C}}$ and $\hat{\mathbb{C}}$, are asymptotically equivalent. Consider the $\hat{\mathbb{C}}$ version of the test and using (3.9) in (3.13) ...rst note that

$$z_{i} = \frac{\frac{3}{\frac{100}{10} X_{i}} \frac{X_{i}^{0} M_{i} X_{i}}{T} \frac{X_{i}^{0} M_{i} X_{i}}{T} \frac{X_{i}^{0} M_{i} X_{i}}{T}}{(T_{i} 1)^{i} \frac{100}{1} M_{i}^{i}}$$
(4.4)

Since (4.1) is a stationary process it then readily follows that under H_0

$$z_i \mid d \hat{A}_p^2$$
, as T $\mid 1$.

Therefore, it is reasonable to conjecture that up to order T^{i1} , $E(z_i)$ and $Var(z_i)$ are given by p and 2p, respectively. The proof of this conjecture turns out to be quite complicated. A rigorous proof is given in Appendix A.3 for the AR(1) case where it is established that indeed

$$E(z_i) = 1 + O^{i}T^{i}^{1}$$
:

Supposing now that this result holds more generally, namely

$$E(z_i) = p + O^{i} T^{i} T^{\dagger},$$
 (4.5)

and write (4.3) as

$$P_{\overline{N}} \stackrel{A}{\longrightarrow} \frac{N^{i} \stackrel{1}{\otimes} \stackrel{i}{i} p}{V_{z}} = P_{\overline{N}} \stackrel{X}{\longrightarrow} \frac{P_{\overline{N}} \stackrel{i}{i} E(z_{i})}{V_{z}} + \frac{1}{N} \stackrel{X}{\longrightarrow} \frac{P_{\overline{N}} [E(z_{i}) i p]}{V_{z}} + O_{p} \stackrel{i}{T} i^{1};$$

where $Var(z_i) = v_z^2$. Hence, using (4.5) we have

$$P_{\overline{N}} \stackrel{A}{\xrightarrow{N^{i}} \stackrel{1}{\Sigma_{i}} \stackrel{p}{\xrightarrow{}}}_{V_{z}} = P_{\overline{N}} \stackrel{A}{\xrightarrow{P}} \stackrel{\mu}{\xrightarrow{}}_{i=1} \stackrel{\mu}{\xrightarrow{}}_{V_{z}} \stackrel{\mu}{\xrightarrow{}}_{V_{z}} \stackrel{P_{\overline{N}}}{\xrightarrow{}}_{V_{z}} \stackrel{A}{\xrightarrow{}}_{V_{z}} \stackrel$$

Under H_0 , the ...rst term in this expression is scaled sums of i.i.d. random variables and tends to N(0; 1) as N ! 1. Therefore, under Assumptions 1-4, and assuming that (4.5) holds, we have (under H_0):

$$\mathbf{c} = \frac{\mathbf{P}_{N}}{N} \frac{\mathbf{A}_{i} \mathbf{S}_{i} \mathbf{p}}{\mathbf{P}_{2p}} \mathbf{P}_{i} \mathbf{N} (0; 1) \text{ as } (N; T) \mathbf{P}^{i} \mathbf{1}, \text{ such that } \frac{\mathbf{P}_{N}}{T} \mathbf{P}_{i} \mathbf{0}. \quad (4.6)$$

One important implication of this result is that the test is valid even when N increases faster than T, so long as N=T! 0. The ¢ test is clearly more restrictive when applied to dynamic models and requires T to be su¢ciently large so that the small sample bias of E(z_i) and V ar(z_i) become negligible relative to N.

4.2. Bias-Corrected Bootstrap Tests of Slope Homogeneity for the AR(1) Model

One possible way of improving over the asymptotic test developed for the AR models would be to follow the recent literature and use bootstrap techniques.⁸ Here we make use of a bias-corrected version of the recursive bootstrap procedure.⁹

One of the main problems in application of bootstrap techniques to dynamic models in small T samples is the fact that the OLS estimates of the individual coe \oplus cients, __i, or their FE (or WFE) counterparts are biased when T is small; a bias that persists with N ! 1. To deal with this problem we focus on the AR(1) case and use the bias-corrected version of $\tilde{\}_{WFE}$ as proposed by Hahn and Kuersteiner (2002).¹⁰ Denoting the bias-corrected version of $\tilde{\}_{WFE}$ by ±, we have

$$\tilde{S}_{WFE} = \tilde{S}_{WFE} + \frac{1}{T} \tilde{S}_{1} + \tilde{S}_{WFE} ;$$
 (4.7)

and estimate the associated intercepts as

⁸For example, see Beran (1988), Horowitz (1994), Li and Maddala (1996) and Bun (2004), although none of these authors make any bias corrections in their bootstrapping procedures.

⁹Bias-corrected estimates are also used in the literature on the derivation of the bootstrap con...dence intervals to generate the bootstrap samples in dynamic AR(p) models. See Kilian (1998), among others.

¹⁰ Bias corrections for the OLS estimates of individual $_{i}$ are provided by Marriott and Pope (1954), and further elaborated by Kendall (1954) and Orcutt and Winokur (1969). Bias corrections for the OLS estimates in the case of higher order AR processes are provided in Shaman and Stine (1988). No bias corrections seem to be available for FE or WFE estimates of AR(p) panel data models in the case of p $_{2}$ 2.

where $y_i = T_{i-1} \mathbf{P}_{t=1}^T y_{it}$, and $y_{i;j-1} = T_{i-1} \mathbf{P}_{t=1}^T y_{i;t_{j-1}}$. The residuals are given by

 $\mathfrak{E}_{it} = y_{it i} \mathfrak{B}_{i;WFE i} \mathfrak{S}_{WFE y_{i;t_{i}}1;}$

with the associated bias-corrected estimator of $\frac{34_i^2}{t}$ given by $\frac{9}{t^2} = (T_i \ 1)^{i} \ ^1 \prod_{t=1}^T (e_{it})^2$. The bth bootstrap sample, $y_{it}^{(b)}$ for i = 1; 2; ...; N and t = 1; 2; ...; T can now be generated as

$$y_{it}^{(b)} = @_{i;WFE} + {}^{\circ}_{\circ}_{WFE} y_{i;t_{i} 1}^{(b)} + \%_{i}{}^{3}{}^{(b)}_{it}; \text{ for } t = 1;2;...;T;$$

where $y_{i0}^{(b)} = y_{i0}$, and ${}^{3}_{it}^{(b)}$ are random draws with replacements from the set of pooled standardized residuals, $\mathfrak{E}_{it}=\mathfrak{A}_{i}$, i = 1; 2; ...; N, and t = 1; 2; ...; T. With $y_{it}^{(b)}$, for i = 1; 2; ...; N and t = 1; 2; ...; T the bootstrap statistics

$$\mathbf{C}^{(b)} = \frac{\mathbf{P}_{\overline{N}}}{\mathbf{N}} \frac{\mathbf{A}_{i} \mathbf{S}^{(b)}_{i} \mathbf{I}}{\mathbf{P}_{\overline{2}}} ; b = 1; 2; \dots; B;$$

can be computed using (3.1) to obtain the bootstrap p-values

$$p_{\rm B} = \frac{1}{B} \frac{\aleph}{{}_{b=1}} I {}^{3} {}^{(b)} i {}^{(b)} i {}^{(c)},$$

where B is the number of bootstrap sample, I (A) takes the value of unity if A > 0 or zero otherwise, and C is the standardized dispersion statistic applied to the actual observations. If $p_B < 0.05$, say, we reject the null hypothesis of slope homogeneity.

5. Finite Sample Properties of Slope Homogeneity Tests

In this section we shall use Monte Carlo techniques to evaluate the ...nite sample properties of the alternative tests of slope homogeneity. We shall focus on our proposed test, \bigcirc de...ned by (3.18) and compare its performance to the Swamy and Hausman tests of slope homogeneity. We also considered the G test of Phillips and Sul (2003), but the G statistic could not be computed due to the singularity problem discussed

in Section 2.3.¹¹ The Swamy's Ŝ statistic is de...ned by (2.10) which we consider to be distributed as $\hat{A}^2_{k(N_i \ 1)}$ under H₀. For the Hausman test (called H test) we make use of the following statistic¹²

$$H = {}^{3}_{MGi} {}^{\overline{}}_{WFE} {}^{9} {}^{1}_{H} {}^{3}_{MGi} {}^{\overline{}}_{WFE} {}^{3}_{S} {}^{2}_{K}; \qquad (5.1)$$

where $^{h}_{MG}$ and $^{e}_{WFE}$ are given by (2.8) and (3.3), respectively, and

with \Re_i^2 and \varkappa_i^2 being de...ned by (2.11) and (3.2), respectively. We report empirical size and power of these tests at 5% nominal level, for various pairs of N and T, including cases where N is much larger than T which is often encountered with micro data sets, as well as when T > N which is more prevalent in the case of macro data sets. We consider panels with strictly exogenous regressors, as well as simple dynamic panels.

Initially, we consider the following simple data generating process (DGP):

$$y_{it} = {}^{\mathbb{R}}_{i} + {}^{-}_{i}x_{it} + {}^{"}_{it}, t = 1; 2; ...; T, i = 1; 2; ...; N;$$

where $\mathbb{R}_i \gg N(1; 1)$, with x_{it} generated as

where $\frac{1}{2}$ » IIDU (0:05; 0:95), v_{it} » IIDN ${}^{i}_{0}$; $\frac{3}{4}^{2}_{ix}$ with $\frac{3}{4}^{2}_{ix}$ » IIDÂ²(1). $\frac{1}{2}_{i}$ and $\frac{3}{4}^{2}_{ix}$ are ...xed across replications. The ...rst 50 observations are discarded to reduce the exect of initial value on the generated values of x_{it} . " ${}^{i}_{it}$ » IID ${}^{i}_{0}$; $\frac{3}{4}^{2}_{it}$ is drawn from (i) standard normal distribution and (ii) $\hat{A}^{2}(2)_{i}$ 2 =2, and $\frac{3}{4}^{2}_{i}$ » IIDÂ²(2)=2.

¹¹In e-mail correspondences Dr. Sul has con...rmed to us that there is an error in equation (27) in Phillips and Sul (2003) that de...nes the G statistic.

¹²We also tried a number of other variants of the Hausman test. But they all performed very similarly.

Under the null hypothesis, $\bar{i} = 1$ for all i, and under the alternative hypothesis, $\bar{i} = 1$ for i = 1; ...; [2N=3], and $\bar{j} \gg N(1; 0:04)$, for j = [2N=3] + 1; ...; N, where [2N=3] is the nearest integer value. \mathbb{R}_{i} , \bar{i} , and $\frac{3}{4}_{i}^{2}$ are ...xed across replications. All combinations of T = 10; 20; 30; 50; 100; 200 and N = 20; 30; 50; 100; 200 are used as sample sizes.

For examining empirical size and power of the tests in the case of regression models with di¤erent numbers of covariates, the following DGP is used:

$$y_{it} = {}^{\circledast}_{i} + \sum_{i=1}^{*} x_{i} {}^{*}_{i} {}^{-}_{i} {}^{*}_{i} + {}^{"}_{it}; i = 1; 2; ...; N; t = 1; 2; ...; T;$$

where, as before, $\mathbb{B}_i \gg [IDN (1; 1), x_{i^t} is generated as speci...ed in (5.3), "_{it} \gg IIDN 0; <math>\frac{3}{4}_i^2$, $\frac{3}{4}_i^2 \gg IID^i k\hat{A}^2(2) = 2^\circ$, k = 1; ...; 4, so that the population \mathbb{R}^2 of individual equations in the panel are invariant to the number of included regressors. Under the null hypothesis $\bar{i}_i = 1$ for all i and `, and under the alternative hypothesis we set $\bar{i}_{11} \gg IIDN (1; 0:04)$ and $\bar{i}_i = \bar{i}_{11}$ for ` = 2; 3; 4. $\mathbb{B}_i, x_{i^t}, \bar{i}_i$, and $\frac{3}{4}_i^2$ are ...xed across replications. For these experiments the sample sizes being considered are the combinations of T = 20, 30 and N = 20; 30; 50; 100; 200.

In the case of dynamic models, two speci...cations are considered. The ...rst is the AR(1) speci...cation

 $y_{it} = (1_{i_{j}})^{\circ} (1_{j_{j}})^{\circ} (1_{j_{j}})^{\circ} (1_{j_{j}})^{\circ} (1_{j_{j}})^{\circ} (1_{j})^{\circ} (1_{j})^{\circ}$

The second dynamic DGP is:

$$y_{it} = (1_{i_{j}} a_{i1} a_{j_{j}} a_{i1} a_{j_{j}} a_{i1} a_$$

where $\mathbb{B}_i \gg N(1;1)$, $\mathbf{z}_2 = 0:2$, and (i) $\mathbf{z}_{1i} = 0:6$ for all i under the null hypothesis, and (ii) $\mathbf{z}_{1i} \gg IIDU(0:4;0:8)$ under the alternative. "it $\gg IIDN^{\mathbf{i}}0$; \mathbf{z}_i^2 with $\mathbf{z}_i^2 \gg IID\hat{A}^2(2)=2$. $\mathbb{B}_{\mathbf{i}}$, \mathbf{z}_{1i} , and \mathbf{z}_i^2 are ...xed across replications. The ...rst 48 observations are discarded. For these experiments, we consider the combinations of sample sizes N and T = 20, 30, 50, 100, 200.

For all experiments 2;000 replications are used.

5.1. Results

Tables 1 to 3 summarize the results for the DGP with strictly exogenous regressors. First, as predicted by the asymptotic theory, Swamy's \$ test tends to over-reject when N is small relative to T, with the extent of over-rejection diminishing as T is increased relative to T. In the case of T = 20 and N = 200, more typical of micro data sets, the empirical size of the \$ test is as much as 34%, and only approaches its nominal size of 5% when T is increased to 200. The standardized dispersion test, \mathbf{C} ; and the Hausman test, H, both have correct sizes. The power of the Ctest also seems to be satisfactory. However, as our theory predicts, the H test has no power in the case of these experiments. Table 2 suggests that the exect of non-normal errors might not be very important for the C test. Size and power estimates in Tables 1 and 2 are very similar. Even when N = 200 and T = 10, where Corollary 3.3 predicts that the e¤ects of error non-normality can be most serious for the ¢ test, the empirical size of the ¢ test is 4:50%. Table 3 reports the size and power of the tests in the case of regression models with dimerent numbers of covariates, k = 1; 2; 3; 4. The results are similar to those provided in Table 1, although, considering that we have controlled for the overall ...t of the regressions, the power of the ¢ test decreases as k increases.

The results for the dynamic DGPs are given in Tables 4 and 5. In the case of these experiments the H test is not valid, and the \hat{S} and ¢ tests are asymptotically equivalent and their validity requires that N=T ! 0 as $(N;T) !^{j} 1$. The results of the Monte Carlo experiments are in line with our theoretical ...ndings. The H statistic is often negative, particularly for values of _ below 0:4, and in cases where it is positive (and hence applicable), the H test exhibits serious over-rejections. The dispersion tests have satisfactory sizes for most combinations of N and T, so long as sis relatively small, namely \cdot 0:4. For these values of the \hat{S} test tends to be more powerful than the ¢ test. The \$ test starts to over-reject as _ is increased to 0:6 and beyond. By comparison, the ¢ test only shows evidence of signi...cant over-rejection when $\ _{\star}$ is increased to 0:9 and only for values of N that are considerably larger than T. For the value of _ in the range of 0:6 to 0:8, the size of the C test continues to be close to its nominal value for all N and T. The same table also illustrates that the C test has reasonable power. Under the alternatives of $_{1}$ » IIDU($_{1}$ 0:2; $_{2}$ + 0:2), the power increases as _ increases, purely because the explanatory power of the estimated model increases. A power comparison of the \hat{S} and $\ensuremath{\mathbb{C}}$ tests for values of $\$ $\$ $\$ 0:6 is complicated by the over-rejection tendency of the former test. Table 5 reports the performance of the tests for the heteroskedastic AR(2) case. Basically the results are similar to those summarized in Table 4 for the AR(1) case.

Table 6 compares the standard normal approximation, (conventional) bootstrap approximation, and Hahn and Kuersteiner (2002) bias-corrected bootstrap approximation of the $\$ test.¹³ The bias-corrected bootstrap procedure controls the size remarkably well, even when the value of $_$ is above 0:8. On the other hand, the conventional bootstrap (non-bias-corrected version) fails to reduce the size distortion of the test. Except when $_$ = 0:2 and T = 20, the bias-corrected bootstrap method yields reasonable power.

Therefore, in practice, when N \cdot T and it is believed that $_{s}$ is

 $^{^{13}}A$ bias-corrected bootstrapped test based on \hat{S} could also be considered, but was not pursued as we expected it to perform very similarly to the bias-corrected bootstrapped test based on \clubsuit .

not close to unity (say the value of $\]$ is below 0:8), the asymptotic version of the $\$ test is recommended. For all N and T, and with the value of $\]$ around 0:9, the Hahn and Kuersteiner (2002) bias-corrected bootstrapped $\$ test seems to be more appropriate.

6. Application: Testing Slope Homogeneity in Earnings Dynamics

In this section we examine the slope homogeneity of the dynamic earnings equations using the Panel Study of Income Dynamics (PSID) data set used in Meghir and Pistaferri (2004). Brie⁺y, these authors select male heads aged 25 to 55 with at least nine years of usable earnings data. The selection process leads to a sample of 2;069 individuals and 31;631 individual-year observations. We further select the individuals who have at least 15 observations, and this leaves us with 1;031 individuals and 19;992 individual-year observations. Following Meghir and Pistaferri (2004), we also categorize the individuals into three education groups: High School Dropouts (HSD, those with less than 12 grades of schooling), High School Graduates (HSG, those with at least a high school diploma, but no college degree), and College Graduates (CLG, those with a college degree or more). In what follows the earning equations for the dimerent educational backgrounds; HSD, HSG, and CLG are denoted by the superscripts e = 1; 2; and 3, and for the pooled sample by 0. The number of individuals in the three categories are N⁽¹⁾ = 249, N⁽²⁾ = 531, and N⁽³⁾ = 251. The panel is unbalanced with t = 1; ..., $T_i^{(e)}$ and i = 1; ...; $N^{(e)}$, and an average time period of around 18 years.

In the research on earnings dynamics, it is standard to adopt a twostep procedure where in the ...rst stage log of real earnings is regressed on a number of control variables such as age, race and year dummies. The dynamics are then modelled based on the residuals from this ...rst stage regression. The use of the control variables and the grouping of the individuals by educational backgrounds is aimed at eliminating (minimizing) the exects of individual heterogeneities at the second stage.

It is, therefore, of interest to examine the extent to which the twostep strategy has been successful in dealing with the heterogeneity problem. With this in mind we follow closely the two-step procedure adopted by Meghir and Pistaferri (2004) and ...rst run regressions of log real earnings, $w_{it}^{(e)}$, on the control variables: a square of "age" (AGE_{it}^{(e)2}), race (WHITE_i^(e)), year dummies (YEAR(t)), region of residence (NE_{it}^(e); CE_{it}^(e); STH_{it}^(e)), and residence in a Standard Metropolitan Statistical Area, (SMSA_{it}^(e)), for each education group e = 0; 1; 2; 3, separately.¹⁴ The residuals from these regressions, which we denote by $y_{it}^{(e)}$, are then used in the second stage to estimate dynamics of the earnings process.

Speci...cally,

$$y_{it}^{(e)} = {}^{(e)}_{i} + {}^{(e)}_{i} y_{it_{i}}^{(e)} + {}^{34}_{i}^{(e)}_{it_{i}}, e = 0; 1; 2; 3,$$

where within each education group (e) is assumed to be homogeneous across the dimerent individuals. Our interest is to test the hypothesis that (e) = (e) for all i in e.

The test results are given in the ...rst panel of Table 7. The ¢ statistics and the associated bootstrapped p values by education groups all lead to strong rejections of the homogeneity hypothesis. Judging by the size of the ¢ statistics, the rejection is stronger for the pooled sample as compared to the sub-samples, con...rming the importance of education as a discriminatory factor in the characterizations of heterogeneity of earnings dynamics across individuals. The test results also indicate the possibility of other statistically signi...cant sources of heterogeneity within each of the education groups, and casts some doubt on the two-step estimation procedure adopted in the literature for dealing with heterogeneity; a point recently emphasized by Alvarez, Browning and Ejrnæs (2002).

In Table 7 we also provide a number of di¤erent FE estimates of (e);

¹⁴Log real earnings are computed as $w_{it}^{(e)} = In LABY_{it}^{(e)} = PCED_t$, where LABY_{it}^(e) is earnings in current US dollar, and PCED_t is the personal consumption expenditure de‡ator, base year 1992.

e = 0; 1; 2; 3, on the assumption of within group slope homogeneity. Given the relatively small number of time series observations available (on average 18), the bias corrections to the FE estimates are quite large. The cross section error variance heterogeneity also plays an important role in this application, as can be seen from a comparison of FE and WFE estimates with the latter being larger. Focussing on the bias-corrected WFE estimates, we also observe that the persistence of earnings dynamics rises systematically from 0.52 in the case of the school drop outs to 0.72 for the college graduates. This seems sensible, and partly re‡ects the more reliable job prospects that are usually open to individuals with a higher level of education.

The homogeneity test results suggest that further exorts are needed also to take account of within group heterogeneity. One possibility would be to adopt a Bayesian approach, assuming that $_{i}^{(e)}$; $i = 1; 2; ...; N^{(e)}$ are draws from a common probability distribution and focus attention on the whole posterior density function of the persistent coe \mathbb{C} cients, rather than the average estimates that tend to divert attention from the heterogeneity problem. Another possibility would be to follow Alvarez, Browning and Ejrnæs (2002) and consider particular parametric functions, relating $_{i}^{(e)}$ to individual characteristics as a way of capturing within group heterogeneity. Finally, one could consider a ...ner categorization of the individuals in the panel; say by further splitting of the education groups or by introducing new categories such as occupational classi...cations. The slope homogeneity tests provide an indication of the statistical importance of the heterogeneity problem, but are silent as how best to deal with the problem.

7. Concluding Remarks

In this paper we have developed simple tests of slope homogeneity in linear panel data models where N could be much larger than T. The proposed tests are based on modi...cations of Swamy's dispersion statistic and examine the cross section "dispersion" of individual slopes weighted by their relative precisions. It is shown that this test is valid when earlier tests based on Hausman (1978) procedure fail to be applicable. The Monte Carlo evidence shows that the proposed ¢ test has good small sample properties in the case of panel data models with strictly exogenous regressors even if N is much larger than T. The ¢ test has satisfactory performance for moderately large T and N of similar orders of magnitude in the case of stationary dynamic models, when the dominant root of the process is not close to unity. In cases where N is much larger than T and/or the dominant root of the dynamic process is near unity, a bias-corrected bootstrap procedure is proposed which seems to perform reasonably well based on Monte Carlo experiments.

The proposed tests are applied to testing the slope homogeneity of the dynamic earnings equations using PSID data, and the results show evidence of slope heterogeneity, even if attention is con...ned to the individuals with similar educational backgrounds.

An important further extension of the tests developed in this paper is to consider testing slope homogeneity in panel data models with multifactor error structures recently examined in Pesaran (2004). This is, however, beyond the scope of the present paper.

. Appendix A: Mathematical Proofs

A.1. Proof of Corollary 3.3

We ...rst note, suppressing the subscript i to simplify the notations, that z_i de...ned by (3.13) can be write as

$$z = \frac{\hat{A}^{0}P\hat{A}}{\hat{A}^{0}M_{c}\hat{A}=(T_{i} 1)} = \frac{\hat{A}^{0}P\hat{A}}{(1+W_{T})}$$
$$= \hat{A}^{0}P\hat{A} 1_{i} W_{T} + \frac{W_{T}^{2}}{1+W_{T}}$$
(A.1)

where

$$W_T = \frac{\hat{A}^0 M_{\hat{i}} \hat{A}}{(T_i 1)} i 1;$$

 $\dot{A} \gg IID(0; I_T)$ and P is de...ned by (3.9). Note also that in this case P is a function of strictly exogenous regressors and by Assumption 5 E [1= (1 + W_T)] is bounded.

By using the moments of the quadratic forms in i.i.d. random variables¹⁵

$$E^{i}A^{0}PA^{c} = k,$$

and

$$E^{\mathbf{f}_{\mathbf{i}}} \dot{A}^{0} P \dot{A}^{\mathbf{f}_{\mathbf{i}}} \dot{A}^{0} M_{\dot{c}} \dot{A}^{\mathbf{f}_{\mathbf{i}}} = {}^{\circ}_{2} tr \left(P^{-} M_{\dot{c}} \right) + tr \left(P \right) tr \left(M_{\dot{c}} \right) + 2tr \left(P M_{\dot{c}} \right),$$

where $^{\circ}_{2}$ is the Pearson's measures of kurtosis, which is zero for normal distributions, and $\overline{}$ signi...es Hadamard product. Since tr (P \overline{M}_{i}) = tr $^{i}P \overline{I}_{T i}P \overline{I}_{T i}P \overline{I}_{T i}$ = T $^{i}^{1}(T_{i} 1)^{i}k$, tr (M_{i}) = T $_{i}$ 1, PM $_{i}$ = P;

$$\mathsf{E}^{\mathbf{\hat{E}}\mathbf{i}} \dot{\mathsf{A}}^{0} \mathsf{P} \dot{\mathsf{A}}^{\mathbf{\hat{C}}\mathbf{i}} \dot{\mathsf{A}}^{0} \mathsf{M}_{\dot{\mathcal{L}}} \dot{\mathsf{A}}^{\mathbf{\hat{C}}\mathbf{x}} = {}^{\circ}_{2} \frac{\mathsf{T} \mathbf{i} \mathbf{1}}{\mathsf{T}} \mathsf{k} + \mathsf{k} (\mathsf{T} \mathbf{i} \mathbf{1}) + 2\mathsf{k},$$

so that the expectation of the second term of (A.1) is

$$\mathsf{E}^{\mathbf{f}_{\mathbf{i}}} \mathsf{A}^{\mathbf{0}} \mathsf{P} \mathsf{A}^{\mathbf{f}} \mathsf{W}_{\mathsf{T}}^{\mathbf{m}} = \frac{\circ_{2} k}{\mathsf{T}} + \frac{2k}{\mathsf{T}_{\mathbf{i}}} \mathsf{I}^{\mathbf{f}}$$

which is $O^{i}T_{i}^{\dagger}$. Also,

$$E^{\mathbf{A}_{\mathbf{P}}} \mathbf{A}^{\mathbf{P}} \mathbf{A}^{\mathbf{P}} \frac{W_{T}^{2}}{1 + W_{T}} + E^{\mathbf{A}_{\mathbf{P}}} \mathbf{A}^{\mathbf{P}} \mathbf{A}^{\mathbf{E}} \mathbf{W}_{T}^{2} \mathbf{E}^{\mathbf{A}_{\mathbf{P}}} \mathbf{E}^{\mathbf{A}_{\mathbf{P}}} \mathbf{E}^{\mathbf{A}_{\mathbf{P}}} = O^{\mathbf{i}} \mathbf{T}^{\mathbf{i}}^{\mathbf{i}}$$

since $E_{d}\dot{A}^{0}P\dot{A}j = O(1)$ and $E_{j}1=(1 + W_{T})j = O(1)$, and $E^{i}W_{T}^{2}^{c} = {}^{\circ}_{2}=T + 2=(T_{i} - 1) = O^{i}T_{i}^{i-1}$; using results in Appendix A.5 of Ullah (2004). Hence,

¹⁵ For example, see Appendix A.5 in Ullah (2004).

Using (3.15) note that

$$P_{\overline{N}}^{3} N^{i} {}^{1}S_{i} k = P_{\overline{N}}^{1} \left[z_{i i} E(z_{i}) \right] + \frac{P_{\overline{N}}}{T} \left(\frac{1}{N} \frac{\varkappa}{1} T[E(z_{i}) i k] + O_{p}^{i} T^{i} \right)^{\ddagger}$$

However, in the light of (A.2) it is clear that

$$\frac{1}{N} \bigotimes_{i=1}^{M} T[k_i \ E(z_i)] = O(1);$$

and if $\stackrel{P}{N}=T ! 0$ as $(N;T) !^{j} 1$ it will also follows that $\stackrel{P}{N}\stackrel{3}{N^{i}}\stackrel{1}{N} = \stackrel{1}{K} !_{d} N(0; var(z_{i}))$ as $(N;T) !^{j} 1$ such that $\stackrel{P}{N}=T ! 0$:

A.2. Proof of Asymptotic Power

Under the local alternatives (de...ned by (3.24))

where

$$\cdot_{iNT} = \Theta_{iT}^{i} \mathbf{x}_{iT} \mathbf{i} \ N^{i} \mathbf{P}_{N}^{i} \mathbf{N}_{N}^{i};$$

$$\tilde{\mathbf{A}}_{\mathbf{P}}^{N} \mathbf{P}_{N}^{i} \mathbf{P}_{N}^{i}$$

$$I_{iNT} = \frac{\pm_i}{N^{1=4}} i \frac{1}{N^{1=4}} \Theta_N^{i1} \frac{\prod_{i=1}^{N} \Theta_{iT} \pm_i}{N};$$

with

and

$$Q_{iT} = \frac{3}{4} i^{2} Q_{iT}; \ \tilde{s}_{iT} = \frac{3}{4} i^{2} s_{iT};$$
 (A.3)

and

Hence

$$N^{i} \stackrel{1=2}{=} S = \frac{T}{N} \underbrace{\overset{\mathbf{X}}{\overset{\mathbf{X}}{=}}}_{i=1}^{a} i^{i} i^{i} \underbrace{\overset{\mathbf{W}}{\overset{\mathbf{W}}{=}}}_{WFE} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{0iT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{i=1}^{a} i^{i} i^{i} \underbrace{\overset{\mathbf{W}}{\overset{\mathbf{W}}{=}}}_{iNT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{iNT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{i=1}^{i} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{iNT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{iNT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{iNT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{iNT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{iNT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf{U}}{\overset{\mathbf{U}}{\overset{\mathbf{U}}{=}}}_{iNT} \underbrace{\overset{\mathbf{U}}{\overset{\mathbf$$

¹⁶This relation generalizes (3.7).

The ...rst term is the component of the test statistic that remains under the null hypothesis and is already shown to be given by

$$\frac{1}{P_{N}} \underset{i=1}{\overset{N}{\longrightarrow}} \cdot \underset{iNT}{\overset{0}{\longrightarrow}} \mathcal{Q}_{iT} \cdot \underset{iNT}{\overset{iNT}{\longrightarrow}} = \frac{1}{P_{N}} \underset{i=1}{\overset{N}{\overset{i}{\longrightarrow}}} z_{i} + O_{p} \overset{i}{\overset{i}{\longrightarrow}} T^{i} \overset{1}{\overset{1}{\overset{i}{\longrightarrow}}} + O_{p} \overset{i}{\overset{N}{\overset{i}{\longrightarrow}}} N^{i} \overset{1=2}{\overset{i=2}{\overset{i}{\longrightarrow}}} :$$

Similarly,

$$\frac{1}{N} = 1 + \frac{N}{N} = 1 + \frac{1}{N} = \frac{1}{N} + \frac{1}{N} = \frac{1}{N} + \frac{1}{$$

and

where

$$\tilde{A}_{NT} = \frac{1}{N} \bigotimes_{i=1}^{\aleph} \stackrel{\tilde{A}}{=} \stackrel{\tilde{A}}{=} \frac{1}{N} \bigotimes_{i=1}^{\tilde{A}} \stackrel{\tilde{A}}{=} \stackrel{\tilde{A}}{=$$

Therefore

$$N^{i^{1=2}}S = \frac{1}{N} \sum_{i=1}^{M} z_i + \tilde{A}_{NT} + O_p N^{i^{1=4}} + O_p i^{T_i^{1}}$$

Using this result in (3.18) we have

$$\begin{tabular}{ll} \label{eq:product} \begin{tabular}{ll} \beg$$

as required.

A.3. Derivation of E (z_i) in the Case of AR(1) Models with Normal Errors Suppressing the subscript i to simplify the notations, the AR(1) model is given by

$$y_{t} = {}^{\textcircled{R}}(1_{i}) + y_{t_{i} 1} + t_{t}, t = 1; 2; ...; T;$$
(A.5)

where [®] is bounded on a compact set, $j_{a}j < 1$, "t » IIDN ⁱ0; $\frac{3}{4}^{c}$ with $0 < \frac{3}{4}^{2} < 1$, and it is assumed that the process is initialized with $y_{0} = ^{@} + "_{0}$, and " $_{0}$ » IIDN ⁱ0; \pm^{2} . The choice of \pm depends on the initialization of the process and will be given by $\pm = \frac{3}{4}^{i}1_{i}_{j}_{a}^{2}$ ^c i ¹⁼² if the process has started at t = i M, with M ! 1. For this model speci...cation z de...ned in (3.13) can be written as

$$z = \frac{i T_{i} T_{i}^{-1=2} M_{i} y_{i}^{-1}}{(T_{i} 1)^{i} M_{i}^{-1} M_{i}^{-1}};$$

where " = ("₁; :::; "_T)⁰, y_{i 1} = (y₀; y₁; :::; y_{T i 1})⁰; and as before $M_{\dot{z}} = I_{T i} \dot{z}_{T} (\dot{z}_{T}^{0} \dot{z}_{T})^{i 1} \dot{z}_{T}^{0}$, with \dot{z}_{T} being a T £ 1 vector of unity.

Rewrite the AR(1) processes in matrix notations as

$$\mathbf{y}^{\alpha} = ^{\mathbf{R}} \boldsymbol{\xi}_{\mathsf{T}+1} + \mathsf{B}^{\mathsf{i}} {}^{1}\mathsf{D}\mathsf{A}; \tag{A.6}$$

where $y^{\mu} = (y_0; y_1; ...; y_T)^0$, $\dot{A} = ("_0=\pm; "_1=3/4; ...; "_T=3/4)^0$ so that $\dot{A} \gg N$ ($O_{T+1 \pm 1}; I_{T+1}$), $O_{T+1 \pm 1}$ is a (T + 1) ± 1 vector of zeros, I_{T+1} is an identity matrix of order T + 1, \vdots_{T+1} is a (T + 1) ± 1 vector of ones, D is a (T + 1) \pm (T + 1) diagonal matrix with its ...rst element equal to \pm and the remaining elements equal to 3/4, and

	2	1 i ₃	0 1	C C C C C C	0 0	3 0 0 7	
B =	ğ	÷	÷	·	÷	: 4.	
	4	0	0	¢¢¢	1	0 5	
		0	0	¢¢¢	د أ	1	

Also $y = G_0 y^{\alpha}$, $y_{i \ 1} = G_1 y^{\alpha}$, where $G_0 = (0_{T \pm 1}; I_T)$ and $G_1 = (I_T; 0_{T \pm 1})$. Hence, noting that $M_{\dot{c}}G_1\dot{c}_{T+1} = 0$ we have $z = \frac{(\dot{A}^0 A \dot{A})^2}{(\dot{A}^0 B \dot{A}) (\dot{A}^0 C \dot{A})},$

$$A = \frac{G_0^0 M_{\dot{z}} G_1 B^{i} {}^1 D}{P_{\overline{T}}}; \qquad (A.7)$$

$$\mathsf{B} = \frac{\mathsf{G}_0^{\mathbb{I}}\mathsf{M}_{\lambda}\mathsf{G}_0}{\mathsf{T}_{\mathsf{i}}\mathsf{I}}; \tag{A.8}$$

$$C = \frac{DB_{i} \, {}^{10}G_{1}^{0}M_{i}G_{1}B_{i} \, {}^{1}D}{T}.$$
 (A.9)

Proposition A.1. Under the stationary AR(1) speci...cation with normal errors given by (A.5), we have

$$E(z) = E \frac{A}{bc} \frac{4(A^{0}AA)^{2}}{bc} i \frac{2(A^{0}AA)^{2}(A^{0}BA)}{b^{2}c}$$

$$i \frac{2(A^{0}AA)^{2}(A^{0}CA)}{bc^{2}} + \frac{(A^{0}AA)^{2}(A^{0}BA)(A^{0}CA)}{b^{2}c^{2}} + O^{i}Ti^{1}(A.10)$$

$$= 1 + O^{i}Ti^{1}, \qquad (A.11)$$

where \dot{A} , A, B, C are de...ned in (A.6), (A.7), (A.8), (A.9), respectively, and tr (B) = b (= 1); and tr (C) = c > 0.

Proof. Firstly we show (A.10), then (A.11). De...ne¹⁷

$$\hat{A}^{I}B\hat{A} = b(1 + X_T);$$

 $\hat{A}^{I}C\hat{A} = c(1 + Y_T);$

¹⁷Note that b = 1 and c is O(1). See Appendix B.

where $X_T = b^{i-1} (\hat{A}^0 B \hat{A}_i b)$, $Y_T \in c^{i-1} (\hat{A}^0 C \hat{A}_i c)$. We also note that since by the assumption $\hat{A} \gg N^{-0} (T_{+1}) \in 1$; I_{T+1} , and B and C are symmetric positive semi-de...nite matrices with rank T i 1, then

$$E \frac{\mu}{A^{0}BA} = O(1);$$
$$E \frac{3}{A^{0}CA} = O(1),$$

and

$$z = \frac{(\hat{A}^{0}A\hat{A})^{2}}{bc} \overset{\mu}{1}_{i} X_{T} + \frac{X_{T}^{2}}{1 + X_{T}} \overset{\Pi}{1}_{i} Y_{T} + \frac{Y_{T}^{2}}{1 + Y_{T}} \overset{\Pi}{1}_{i}$$
$$= \frac{(\hat{A}^{0}A\hat{A})^{2}}{bc} \cdot (1_{i} X_{T})(1_{i} Y_{T}) + \frac{Y_{T}^{2}}{1 + Y_{T}} i \frac{X_{T}Y_{T}^{2}}{1 + Y_{T}} + \frac{X_{T}^{2}}{1 + X_{T}} i \frac{Y_{T}X_{T}^{2}}{1 + X_{T}} + \frac{Y_{T}^{2}X_{T}^{2}}{(1 + X_{T})(1 + Y_{T})} \cdot$$

As B and C are symmetric positive semi-de...nite matrices, by Lemma B.1 in Appendix B

$$E^{f}X_{T}^{2^{n}} = \frac{tr^{i}B^{2^{c}}}{[tr(B)]^{2}} = O^{i}T_{i}^{1^{c}}, \quad E^{f}Y_{T}^{2^{n}} = \frac{tr^{i}C^{2^{c}}}{[tr(C)]^{2}} = O^{i}T_{i}^{1^{c}},$$

ш

so that

$$E[z] = E \frac{(\dot{A}^{0}A\dot{A})^{2}}{bc} (1_{i} X_{T}) (1_{i} Y_{T}) + O^{i}T^{i}^{\dagger}^{\dagger}$$

$$= E \frac{4(\dot{A}^{0}A\dot{A})^{2}}{bc}_{i} \frac{2(\dot{A}^{0}A\dot{A})^{2}(\dot{A}^{0}B\dot{A})}{b^{2}c}_{i} \frac{2(\dot{A}^{0}A\dot{A})^{2}(\dot{A}^{0}C\dot{A})}{b^{2}c} + O^{i}T^{i}^{\dagger}^{\dagger},$$

$$\frac{(\dot{A}^{0}A\dot{A})^{2}}{b^{2}c^{2}} + O^{i}T^{i}^{\dagger}^{\dagger},$$

since

$$E = \frac{(\dot{A}^{0}A\dot{A})^{2}}{bc} \frac{Y_{T}^{2}}{1+Y_{T}} = C = \frac{(\dot{A}^{0}A\dot{A})^{2}}{bc} = E = \frac{1}{1+Y_{T}} = E^{T}Y_{T}^{2}$$
$$= O^{T}E^{T}Y_{T}^{2} = O^{T}T^{T}T^{T}$$

and

$$E = \frac{(\hat{A}^{0}A\hat{A})^{2}}{bc} \frac{X_{T}Y_{T}^{2}}{1 + X_{T}} = E = \frac{(\hat{A}^{0}A\hat{A})^{2}}{bc} = E jX_{T} j E = \frac{1}{1 + X_{T}} = E Y_{T}^{2}$$
$$= O^{i}T i^{j}$$

Similarly E^{-h} i h $X_T^2 (1 + X_T)^{i}$ and E^{-h} i h $Y_T X_T^2 (1 + Y_T)^{i}$ and E^{-h} i h $Y_T X_T^2 (1 + Y_T)^{i}$ are at most $O^{i}T^{i}$, and

$$E = \frac{(\hat{A}^{0}A\hat{A})^{2}}{bc} \frac{Y_{T}^{2}X_{T}^{2}}{(1 + X_{T})(1 + Y_{T})} = E = \frac{(\hat{A}^{0}A\hat{A})^{2}}{bc} = E = \frac{1}{1 + Y_{T}} = E = \frac{1}{1 + X_{T}} = E = Y_{T}^{2} = E = X_{T}^{2}$$
$$= O^{i}E^{i}Y_{T}^{2} = E^{i}X_{T}^{2} = O^{i}T^{i}2^{c}:$$

Consider now (A.11). By using the moments of the quadratic forms in i.i.d. standard normal random variables¹⁸

$$\mathsf{E}^{\mathbf{n}_{i}} \mathsf{A}^{0} \mathsf{A} \mathsf{A}^{\mathbf{c}_{2}^{I}} = [\mathsf{tr}(\mathsf{A})]^{2} + \mathsf{tr}^{i} \mathsf{A}^{2} + \mathsf{A}^{0} \mathsf{A}^{\mathbf{c}}:$$

Using (B.2) in Appendix B

$$\mathsf{E}^{\mathbf{h}_{\mathbf{i}}} \dot{\mathsf{A}}^{\mathbf{0}} \mathsf{A} \dot{\mathsf{A}}^{\mathbf{c}_{2}\mathbf{i}} = \mathsf{c} + \mathsf{O}^{\mathbf{i}} \mathsf{T}^{\mathbf{i}}^{\mathbf{1}^{\mathbf{c}}}.$$

Also, using results in Ullah (2004, Appendix A.4), together with (B.2) and (B.3) in Appendix B, and noting that tr (AC) = tr ($A^{I}C$),

$$E^{\mathbf{n}_{i}} \dot{A}^{\emptyset} A \dot{A}^{\pounds_{2}} \dot{i} \dot{A}^{\emptyset} C \dot{A}^{\pounds} = [tr (A)]^{2} tr (C) + 4tr \dot{i} A^{2} C^{\pounds} + 2tr \dot{i} A^{\emptyset} A C^{\pounds} + 2tr \dot{i} A A^{\emptyset} C^{\pounds} + 4tr (A) tr (AC) + tr (C) tr \dot{i} A^{2} + A^{\emptyset} A^{\pounds} = tr (C) tr \dot{i} A^{\emptyset} A^{\pounds} + O(T^{i}) = c^{2} + O(T^{i}).$$

Next, again using results in Ullah (2004, Appendix A.4), together with (B.2) and (B.4) in Appendix B

$$E^{\mathbf{n}_{i}} \dot{A}^{0} A \dot{A}^{\mathbf{c}_{2}} \dot{i} \dot{A}^{0} B \dot{A}^{\mathbf{c}_{i}} = [tr (A)]^{2} tr (B) + 4tr^{i} A^{2} B^{\mathbf{c}} + 2tr^{i} A^{0} A B^{\mathbf{c}} + 2tr^{i} A A^{0} B^{\mathbf{c}}$$
$$+ 4tr (A) tr (AB) + tr (B) tr^{i} A^{2} + A^{0} A^{\mathbf{c}}$$
$$= tr (B) tr^{i} A^{0} A^{\mathbf{c}} + O(T^{i})$$
$$= bc + O(T^{i}).$$

Finally, using results in Ullah (2004, Appendix A.4), together with (B.2) - (B.6) in Appendix B,

$$E^{h_{i}} {}_{u_{0}} A^{u_{0}} {}_{2} {}_{i_{u_{0}}} B^{u_{0}} C^{u_{0}} C^{u_{0}} C^{u_{0}}$$

$$= [tr (A)]^{2} tr (B) tr (C)$$

$$+ 8 tr (A) tr^{i} ABC + A^{0} BC^{t}$$

$$+ tr (B)^{t} {}_{4} tr^{i} A^{2} C^{t} + 2 tr^{i} A^{0} AC^{t} + 2 tr^{i} AA^{0} C^{t_{m}}$$

$$+ tr (C)^{t} {}_{4} tr^{i} A^{2} B^{t} + 2 tr^{i} A^{0} AB^{t} + 2 tr^{i} AA^{0} B^{t_{m}}$$

$$+ 2 tr^{i} A^{2}^{t} tr (BC) + 2 tr^{i} A^{0} A^{t} tr (BC) + 8 tr (AB) tr (AC)$$

$$+ 2 [tr (A)]^{2} tr (BC) + 4 tr (A) tr (B) tr (AC) + 4 tr (A) tr (C) tr (AB)$$

$$+ tr (B) tr (C) tr^{i} A^{2}^{t} + tr (B) tr (C) tr^{i} A^{0} A^{t}$$

$$+ 8 tr^{i} A^{2} BC^{t} + 8 tr^{i} A^{0} ABC^{t} + 8 tr^{i} AA^{0} BC^{t} + 8 tr^{i} A^{2} CB^{t}$$

$$= tr (B) tr (C) tr^{i} A^{0} A^{t} + O(T^{i})$$

$$= bc^{2} + O(T^{i}).$$

Therefore, we can conclude

$$E(z) = 1 + O(T^{i});$$

as required.

¹⁸For example, see Appendix A.4 Ullah (2004).

. Appendix B: Lemmas

Lemma B.1 Suppose H is a (T £ T) symmetric positive semi-de...nite matrix with bounded eigenvalues where $^{\circ}_{t}(H) = 0$ for t = 0; 1; ...; T, where $^{\circ}_{t}(H) = O(1)$. Then,

$$\frac{\text{tr}^{i} \text{H}^{2}^{c}}{[\text{tr}(\text{H})]^{2}} = O^{i} \text{T}^{i}^{1} \text{C}^{c}. \tag{B.1}$$

Proof. We ...rst note that

$$\frac{\mathrm{tr}^{\mathbf{i}} \mathrm{H}^{2}}{[\mathrm{tr}(\mathrm{H})]^{2}} = {}^{\mathbf{P}}_{\mathbf{P}}_{\underbrace{\mathsf{t}=1}^{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{t}}(\mathrm{H})}_{\mathbf{P}}_{\underbrace{\mathsf{t}=1}^{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{t}}(\mathrm{H})}_{\mathsf{T}} = \frac{\underbrace{\mathsf{T}^{\mathsf{i}}}_{\mathsf{T}} \mathop{\mathsf{P}}_{\underbrace{\mathsf{t}=1}^{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{t}}(\mathrm{H})}_{\mathsf{T}}_{\mathsf{T}} \underbrace{\mathsf{P}}_{\underbrace{\mathsf{T}}}_{\mathsf{T}} \underbrace{\mathsf{P}}_{\mathsf{T}}^{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{t}}(\mathrm{H})}_{\mathsf{T}}_{\mathsf{T}} \underbrace{\mathsf{P}}_{\mathsf{T}}^{\mathsf{P}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}}} \underbrace{\mathsf{P}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}_{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}} \circ \overset{\mathsf{P}}{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}} \circ \overset{\mathsf{P}}{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}} \circ \overset{\mathsf{P}}{\mathsf{T}} \circ \overset{\mathsf{P}}{\mathsf{T}}} \circ \overset{\mathsf{P}}{\mathsf{T}} \circ \overset{\mathsf{P}} \circ {\mathsf{P}} \circ {\mathsf{T}} \circ {\mathsf{P}}$$

But

$$\tilde{\mathbf{A}}_{\mathbf{X}} \underbrace{\mathbf{P}}_{t=1}^{\circ} \underbrace{\mathbf{P}}_{t(\mathbf{H})} = \underbrace{\mathbf{X}}_{t=1} \underbrace{\mathbf{P}}_{t=1}^{\circ} \underbrace{\mathbf{P}}_{t(\mathbf{H})} + 2 \underbrace{\mathbf{X}}_{t>t^{\circ}} \underbrace{\mathbf{P}}_{t(\mathbf{H})} \underbrace{\mathbf{P}}_{t(\mathbf{H})} \underbrace{\mathbf{P}}_{t=1} \underbrace{\mathbf{P}}_{t=1} \underbrace{\mathbf{P}}_{t=1} \underbrace{\mathbf{X}}_{t=1} \underbrace{\mathbf{P}}_{t=1} \underbrace{\mathbf{P}}$$

S0

Hence (B.1) allows considering that $\Pr_{t=1}^{T} \circ_{t}(H) = O(T)$ and $\Pr_{t=1}^{T} \circ_{t}^{2}(H) = O(T)$. Lemma B.2 Consider the non-stochastic matrices A, B, and C de...ned by (A.7), (A.8), and (A.9) in Appendix A.3, respectively. Then,

tr (B) = 1; tr
$${}^{i}A^{0}A^{c}$$
 = tr (C) = O (1); tr (A) = O T_{i}^{3}T_{i}^{1=2}; tr ${}^{i}A^{2}c^{c}$ = O ${}^{i}T_{i}^{1}T_{i}^{c}$; (B.2)

tr (BC) =
$$O^{i}T_{i}^{\dagger}$$
; tr $i^{i}A^{0}BC^{c} = O^{i}T_{i}^{3=2}$; tr (ABC) = $O^{i}T_{i}^{3=2}$; (B.5)

and

tr
$$^{i}A^{2}BC^{\ddagger}$$
; tr $^{i}A^{0}ABC^{\ddagger}$; tr $^{i}AA^{0}BC^{\ddagger}$; tr $^{i}A^{2}CB^{\ddagger}$;
tr (ABAC); tr $^{i}A^{0}BAC^{\ddagger}$; tr $^{i}ABA^{0}C^{\ddagger}$ are at most O $^{i}T^{i}2^{\ddagger}$: (B.6)

Proof.

We ... rst note that

and

The matrices $G_0^{I}M_{i}G_0$ and $G_1^{I}M_{i}G_1$ are idempotent with two zero eigenvalues and T i 1 unit eigenvalues. Therefore, noting that B is a lower triangular matrix with unit diagonal

elements and D is a diagonal matrix with $\frac{4}{2}max = Max(\frac{3}{2}; \pm) < K < 1$ we have, using (A.9),

$$0 \cdot \circ_t(C) \cdot \frac{\frac{3}{4}\max}{T};$$

where $o_t(C)$ for t = 0; 1; ...; T are the eigenvalues of C. Also it is easily veri...ed that

$$G_0 G_0^{\emptyset} = I_T , A^{\emptyset} A = C; \qquad (B.7)$$

and

$$A^{0}B = \frac{B^{0_{i}} {}^{1}G_{1}^{0}M_{j}G_{0}G_{0}^{0}M_{j}G_{0}}{T^{1=2}(T_{i} 1)} = (T_{i} 1)^{i} {}^{1}A^{0};$$
(B.8)

$$AA^{0}B = (T_{i} 1)^{i}AA^{0}$$
: (B.9)

To prove the results in (B.2), we ...rst note that

tr(B) = 1; tr(C) =
$$\frac{\mathbf{X}}{t=0}^{\circ} t(C) \cdot \frac{(T+1)\frac{3}{max}}{T} = O(1).$$
 (B.10)

Since $\frac{3}{max}$ is bounded, to simplify the derivations and without loss of generality in what follows we set $\pm = \frac{3}{4} = 1$; (so that $D = I_{T+1}$) and note that

$$B^{i 1} = \begin{cases} 2 & & & & 3 \\ 1 & 0 & \text{ctc} & 0 & 0 \\ 2 & 1 & \text{ctc} & 0 & 0 \\ 3 & 1 & \text{ctc} & 0 & 0 \\ 2 & \vdots & \vdots & \ddots & \vdots & \vdots \\ 7 & 1 & 7 & 2 & \text{ctc} & 1 & 0 \\ 7 & 7 & 1 & \text{ctc} & 1 \\ 1 & \text{ct$$

where

$$g_{\hat{}} = \frac{1}{T} \sum_{j=0}^{X} j_{j} = \frac{1}{T} \frac{\tilde{A}_{\hat{}} j_{\hat{}}}{1_{\hat{}} j_{\hat{}}} = O^{\hat{I}} T^{\hat{I}} (\text{since } j_{\hat{}} j < 1), \text{ for } = 0; 1; ...; T_{\hat{I}} 1.$$

Therefore,

tr (A) =
$$\frac{i}{P_{T}} \frac{1}{T} \sum_{i=0}^{W^{2}} g_{i} = \frac{i}{T} \frac{1}{T} \sum_{i=0}^{W^{2}} \frac{1}{1} \frac{1}{i} \sum_{i=0}^{T+1} \frac{1}{1} = O(T^{i})$$
 (B.12)

Consider now tr ${}^{i}A^{2}^{c}$. Using (B.11)

$$\operatorname{tr}^{i} A^{2^{c}} = T^{i} T^{i} E^{2^{c}} + \operatorname{tr}^{i} F^{2^{c}} T^{i} 2\operatorname{tr} (EF)^{*}$$
: (B.13)

But it is easily seen that

$$tr^{i}E^{2^{c}} = 0;$$

$$tr^{i}F^{2^{c}} = g;$$

$$tr^{i}F^{2^{c}} = g;$$

$$tr(EF) = \frac{\sqrt{3}^{2^{c}}}{1_{i}} \frac{1_{i}}{1_{i}} \frac{1_$$

which together with (B.13) establishes that $\text{tr}^{i} A^{2^{\text{c}}} = O^{i} T^{i}^{1^{\text{c}}}$. To prove the results in (B.3), we observe that¹⁹

$$\operatorname{tr}^{\mathbf{i}} A^{\emptyset} A C^{\mathbf{c}} = \operatorname{tr}^{\mathbf{i}} C^{2^{\mathbf{c}}} = \frac{\mathbf{X}}{t=0} \circ^{2}_{t}(C) \cdot \frac{\mathcal{X}_{max}}{T} = O^{\mathbf{i}} T^{\mathbf{i}-1^{\mathbf{c}}}:$$

By Cauchy-Schwarz inequality

$${}^{\mathbf{f}} \operatorname{tr}^{\mathbf{i}} \mathsf{A} \mathsf{A}^{0} \mathsf{C}^{\mathbf{k} \mathbf{n}_{2}} \cdot \operatorname{tr}^{\mathbf{i}} \mathsf{A} \mathsf{A}^{0} \mathsf{A} \mathsf{A}^{0} \operatorname{tr}^{\mathbf{i}} \mathsf{C}^{0} \mathsf{C}^{\mathbf{c}} = \operatorname{tr}^{\mathbf{3}} {}^{\mathbf{f}} \mathsf{A}^{0} \mathsf{A}^{\mathbf{n}_{2}} \operatorname{tr}^{\mathbf{i}} \mathsf{C}^{2} = {}^{\mathbf{f}} \operatorname{tr}^{\mathbf{i}} \mathsf{C}^{2} {}^{\mathbf{c} \mathbf{n}_{2}};$$

which establishes $jtr(AA^{0}C)j = O^{i}T^{i-1}$. Similarly, again by Cauchy-Schwarz inequality and noting that $A^{0}A = C$,

$${}^{\mathbf{f}} \operatorname{tr}^{\mathbf{i}} A^{2} C^{\mathbf{f} \mathbf{a}_{2}} \cdot \operatorname{tr}^{\mathbf{i}} A A^{0} A^{0}^{\mathbf{f}} \operatorname{tr}^{\mathbf{i}} C^{2^{\mathbf{f}}} = \operatorname{tr}^{\mathbf{i}} A A^{0} C^{\mathbf{f}} \operatorname{tr}^{\mathbf{i}} C^{2^{\mathbf{f}}};$$

which establishes $\operatorname{tr}^{i} A^{2} C^{\mathbb{C}} = O^{i} \operatorname{T}_{i} \operatorname{t}^{\mathbb{C}}$. To derive the order of tr (A⁰C), again by Cauchy-Schwarz inequality

$${}^{\mathbf{f}} \operatorname{tr}{}^{\mathbf{i}} \mathsf{A}^{0} \mathsf{C}^{\mathbf{f} \mathbf{a}_{2}} \cdot \operatorname{tr}{}^{\mathbf{i}} \mathsf{A}^{0} \mathsf{A}^{\mathbf{f}} \operatorname{tr}{}^{\mathbf{i}} \mathsf{C}^{0} \mathsf{C}^{\mathbf{f}} = \operatorname{tr}(\mathsf{C}) \operatorname{tr}(\mathsf{C}^{2}):$$

Therefore, since tr(C) = O(1), it follows that $jtr(A^{0}C)j = O(T^{i})$. To establish the results in (B.4), by Cauchy-Schwarz inequality

$${}^{\mathbf{f}} \mathrm{tr}^{\mathbf{i}} \mathsf{A}^2 \mathsf{B}^{\mathbf{c} \mathbf{a}_2} \cdot \mathrm{tr}^{\mathbf{i}} \mathsf{A} \mathsf{A}^0 \mathsf{C}^{\mathbf{c}} \mathrm{tr}^{\mathbf{i}} \mathsf{B}^{2^{\mathbf{c}}}.$$

But

$$\operatorname{tr}^{\mathbf{i}} B^{2}{}^{\mathbf{c}} = \frac{\operatorname{tr}^{\mathbf{i}} (G_{0}^{0} M_{\lambda} G_{0})^{2}}{(T_{\mathbf{i}} 1)^{2}} = \frac{\operatorname{tr} [(G_{0}^{0} M_{\lambda} G_{0})]}{(T_{\mathbf{i}} 1)^{2}} = \frac{1}{T_{\mathbf{i}} 1} = O^{\mathbf{i}} T^{\mathbf{i}} 1^{\mathbf{c}},$$

hence, $tr^{\dagger}A^{2}B = O^{\dagger}T^{\dagger}$. Similarly,

$$\frac{\mathbf{f}_{\text{tr}}^{\mathbf{i}} \mathbf{A}^{0} \mathbf{A} \mathbf{B}^{\mathbf{f} \mathbf{a}_{2}}}{\mathbf{a}_{2}} = [\text{tr} (\mathbf{C} \mathbf{B})]^{2} \cdot \text{tr}^{\mathbf{i}} \mathbf{C}^{2^{\mathbf{f}}} \text{tr}^{\mathbf{i}} \mathbf{B}^{2^{\mathbf{f}}} = \mathbf{O}^{\mathbf{i}} \mathbf{T}^{\mathbf{i}}^{2^{\mathbf{f}}};$$

¹⁹Recall that $C^0 = C$ and $A^0A = C$.

which establishes jtr $(A^{\emptyset}AB)j = O^{i}T_{i}^{\dagger}^{\dagger}$. Using (B.9)

$$tr^{i}AA^{0}B^{c} = (T_{i} 1)^{i} tr^{i}A^{0}A^{c} = (T_{i} 1)^{i} tr(C) = O^{i}T_{i}^{1}C^{c}$$

Also

$$tr (AB) = T^{i} {}^{1=2}(T_{i} 1)^{i} {}^{1}tr {}^{i}G_{0}^{0}M_{i}G_{1}B^{0}{}^{i} {}^{1}G_{0}^{0}M_{i}G_{0}^{}$$

= T^{i} {}^{1=2}(T_{i} 1)^{i} {}^{1}tr {}^{i}G_{0}^{0}M_{i}G_{1}B^{0}{}^{i} {}^{1}{}^{c} = \frac{1}{T_{i} 1}tr (A) = O T^{i} {}^{3=2} :

To prove the results in (B.5), a further application of the Cauchy-Schwarz inequality to A and BC now yields

$$\begin{array}{rcl} {}^{f} \mathrm{tr} \, {}^{i} \mathsf{A}^{0} \mathsf{BC}^{\mathsf{C} \mathsf{x}_{2}} & \cdot & \mathrm{tr}^{i} \mathsf{A}^{0} \mathsf{A}^{\mathsf{C}} \, \mathrm{tr}^{i} \mathsf{C}^{0} \mathsf{B}^{0} \mathsf{BC}^{\mathsf{C}} = \mathrm{tr}(\mathsf{C}) \mathrm{tr}^{i} \mathsf{B}^{2} \mathsf{C}^{2}^{\mathsf{C}}; \\ \left[\mathrm{tr} \, (\mathsf{A} \mathsf{B} \mathsf{C}) \right]^{2} & \cdot & \mathrm{tr}^{i} \mathsf{A} \mathsf{A}^{0}^{\mathsf{C}} \, \mathrm{tr}^{i} \mathsf{C}^{0} \mathsf{B}^{0} \mathsf{B} \mathsf{C}^{\mathsf{C}} = \mathrm{tr}(\mathsf{C}) \mathrm{tr}^{i} \mathsf{B}^{2} \mathsf{C}^{2}^{\mathsf{C}}; \end{array}$$

But as easily seen

so that

$$[tr^{\mathbf{i}}B^{2}C^{2}] \cdot O^{\mathbf{i}}T^{\mathbf{i}} 3^{\mathbf{c}},$$

and hence

$$\int_{a}^{b} d^{0}BC^{\dagger} = O(T^{i}); \text{ and } jtr(ABC)j = O(T^{i})$$

Similarly,

$$[\text{tr}(BC)]^2 \cdot \text{tr}^{i} B^2^{c} \text{tr}^{i} C^2^{c} = O^{i} T^{i^2}$$

and $jtr(BC)j = O(T^{i-1})$: Finally, the various higher order terms in (B.6) can be established following similar lines. Firstly, i. ¢

tr
$$A^{\parallel}ABC = tr(BC^2) \cdot tr(B^2)tr(C^4) = O(T^{i^4});$$

so that $tr(BC^2) = O(T^{i^2});$ and

$$\begin{array}{l} {}^{f} \operatorname{tr}^{i} A^{2} B C^{{}^{f} \pi_{2}} \\ {}^{f} \operatorname{tr}^{i} A^{2} C B^{{}^{f} \pi_{2}} \\ {}^{f} \operatorname{tr}^{i} A^{2} C B^{{}^{f} \pi_{2}} \end{array} \cdot \operatorname{tr}^{i} A A^{\emptyset} C^{{}^{f}} \operatorname{tr}^{i} C^{2} B^{2^{{}^{f}}} = O^{i} T^{i} {}^{4^{{}^{f}}};$$

Similarly,

$$[\operatorname{tr}(\mathsf{ABAC})]^2 \cdot \operatorname{tr}^{\mathbf{i}} \mathsf{ABB}^{\mathbb{I}} \mathsf{A}^{\mathbb{I}}^{\mathsf{C}} \operatorname{tr}^{\mathbf{i}} \mathsf{C}^{\mathbb{I}} \mathsf{A}^{\mathbb{I}} \mathsf{AC}^{\mathsf{C}} = \operatorname{tr}^{\mathbf{i}} \mathsf{B}^2 \mathsf{C}^{\mathsf{C}} \operatorname{tr}^{\mathbf{i}} \mathsf{C}^3^{\mathsf{C}} = \mathsf{O}(\mathsf{T}^{\mathsf{i}})^4$$

Furthermore,

$${}^{\mathbf{f}} \operatorname{tr}^{\mathbf{i}} \mathsf{A} \mathsf{A}^{0} \mathsf{B} \mathsf{C}^{\mathsf{C}^{\mathbf{a}_{2}}} = {}^{\mathbf{f}} \operatorname{tr}^{\mathbf{i}} \mathsf{A}^{0} \mathsf{B} \mathsf{C} \mathsf{A}^{\mathsf{C}^{\mathbf{a}_{2}}} \cdot \operatorname{tr}^{\mathbf{i}} \mathsf{A}^{0} \mathsf{B} \mathsf{B}^{0} \mathsf{A}^{\mathsf{C}} \operatorname{tr}^{\mathbf{i}} \mathsf{A}^{0} \mathsf{C}^{0} \mathsf{C} \mathsf{A}^{\mathsf{C}} = \operatorname{tr}^{\mathbf{i}} \mathsf{B}^{2} \mathsf{A} \mathsf{A}^{0} {}^{\mathsf{C}} \operatorname{tr}^{\mathbf{i}} \mathsf{C}^{2} \mathsf{A} \mathsf{A}^{0} {}^{\mathsf{C}};$$

and

$$\begin{array}{ccc} {}^{f} tr {}^{i} A^{\emptyset} BAC^{{}^{f} \pi_{2}} & tr {}^{i} A^{\emptyset} BB^{\emptyset} A^{{}^{f}} tr {}^{i} C^{\emptyset} A^{\emptyset} AC^{{}^{f}} = tr {}^{i} B^{2} AA^{\emptyset} {}^{f} tr {}^{i} C^{3} {}^{c}; \\ {}^{f} tr {}^{i} ABA^{\emptyset} C^{{}^{f} \pi_{2}} & tr {}^{i} ABB^{\emptyset} A^{\emptyset} {}^{f} tr {}^{i} C^{\emptyset} AA^{\emptyset} C^{{}^{f}} = tr {}^{i} B^{2} C^{{}^{f}} tr {}^{i} C^{2} AA^{\emptyset} {}^{f}; \\ \end{array}$$

Also using (B.8) and (B.9) we have

$$tr^{i}AA^{0}B^{2}{}^{c} = \frac{1}{T_{i}}tr^{i}AA^{0}B^{c} = \frac{1}{(T_{i})^{2}}tr^{i}AA^{0}{}^{c} = \frac{tr(A^{0}A)}{(T_{i})^{2}} = O(T^{i^{2}}):$$

$$f^{t}tr^{i}C^{2}AA^{0}{}^{c} = \frac{f}{tr}^{i}AA^{0}C^{2}{}^{c} + tr^{i}AA^{0}AA^{0}{}^{c} tr^{i}C^{4}{}^{c} = tr^{i}A^{0}AA^{0}A^{c} tr^{i}C^{4}{}^{c}$$

$$= tr(C^{2})tr^{i}C^{4}{}^{c} = O(T^{i^{4}}):$$

Finally, it is easily established that

$$\operatorname{tr}^{\mathbf{i}} B^{2} C^{\mathbf{c}} = O(T^{i^{2}}); \operatorname{tr}^{\mathbf{i}} C^{3^{\mathbf{c}}} = O(T^{i^{2}}):$$

Hence all the terms in (B.6) are of order $O(T^{i})$.

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NnT	10	20	30	50	100	200
Size						
Ŝ test						
20	25:25	11:70	9:75	7:70	6:00	6:40
30	31:20	13:45	10:60	8:10	5:45	5:00
50	39:45	17:75	10:70	8:70	6:50	6:00
100	61:05	21:15	15:00	10:65	7:50	5:95
200	82:35	33:90	18:30	12:90	7:95	6:65
H test						
20	7:95	6:55	4:55	6:35	5:20	4:10
30	8:75	6:95	6:50	4:70	4:90	5:35
50	6:60	5:25	5:95	4:80	5:15	5:50
100	6:85	6:20	5:85	5:00	5:30	5:40
200	9:10	5:90	5:40	6:30	5:80	5:30
¢ test						
20	4:60	4:20	3:70	3:95	3:80	4:05
30	4:95	4:50	4:30	4:75	3:80	4:15
50	4:85	4:80	4:05	4:35	4:60	4:90
100	4:40	5:00	4:95	5:60	5:00	4:80
200	5:20	5:75	4:55	4:85	4:70	4:95
Power						
S test						
20	29:05	21:80	23:30	31:00	58:65	88:80
30	43:45	45:25	52:40	81:80	99:10	100:00
50	64:50	68:05	80:15	96:65	100:00	100:00
100	100:00	100:00	100:00	100:00	100:00	100:00
200	100:00	100:00	100:00	100:00	100:00	100:00
H test						
20	6:65	5:15	5:60	5:70	5:40	3:55
30	7:15	5:70	5:55	5:20	5:30	5:90
50	6:70	5:75	5:20	5:10	5:90	5:05
100	6:00	6:30	5:90	5:20	5:85	5:45
200	6:35	6:30	4:65	5:00	6:10	5:70
¢ test						
20	4:65	6:90	9:45	16:60	43:65	82:55
30	7:10	15:65	26:45	65:65	9 8:15	100:00
50	8:55	26:85	46:80	85:95	99:90	100:00
100	26:80	71:35	99:25	100:00	100:00	100:00
200	44:95	99:15	100:00	100:00	100:00	100:00

Table 1 : Size and Power of the Slope Homogeneity Tests, with Strictly Exogenous Regressors: Normal Errors

Notes: s test, c test; and H test statistics are de...ned in (2.10), (3.18), and (5.1), respectively. The DGP is speci...ed as $y_{it} = \circledast_i + \neg_i x_{it} + "_{it}$, t = 1; 2; ...; T, i = 1; 2; ...; N where $\circledast_i \gg N(1; 1)$, with x_{it} generated as $x_{it} = \circledast_i (1_i \ \aleph_i) + \aleph_i x_{it_i} 1 + (1_i \ \aleph_i^2)^{1=2} v_{it}; t = i \ 49; ...; 0; ...; T$, i = 1; 2; ...; N where $\aleph_i \gg IIDU(0:05; 0:95)$, $v_{it} \gg IIDN(0; \aleph_{ix}^2)$ with $\aleph_{ix}^2 \gg IIDA^2(1)$. \aleph_i and \aleph_{ix}^2 are ...xed across the replications. The ...rst 50 observations are discarded to reduce the exect of initial value on the generated values of x_{it} . " $_{it} \gg IIDN(0; \aleph_i^2)$, with $\aleph_i^2 \gg IIDA^2(2)=2$. Under the null hypothesis, $\neg_i = 1$ for all i, and under the alternative hypothesis, $\neg_i = 1$ for i = 1; ...; [2N=3], and $\neg_j \gg N(1; 0:04)$, for j = [2N=3] + 1; ...; N, where [2N=3] is the nearest integer value. \circledast_i, \neg_i , and \aleph_i^2 are ...xed across replications. All tests are conducted at 5% nominal level. All the experiments are based on 2; 000 replications.

NnT	10	20	30	50	100	200
Size						
Ŝ test						
20	23:85	13:45	8:50	5:85	5:30	5:55
30	30:90	13:10	10:15	8:40	6:40	4:75
50	40:70	15:50	11:15	8:85	6:30	6:80
100	59:65	23:00	14:70	9 :55	7:35	5:35
200	81:50	32:35	19:30	11:40	8:60	6:40
H test						
20	6:45	6:60	6:45	4:95	4:90	5:90
30	7:60	5:75	5:90	5:20	5:00	5:05
50	7:35	6:10	5:70	5:15	5:30	4:50
100	6:75	6:55	5:25	5:05	5:25	4:40
200	8:05	6:35	6:15	5:40	4:70	5:60
¢ test						
20	3:50	4:35	3:30	3:35	3:95	3:80
30	4:65	3:75	4:10	4:30	4:45	4:20
50	5:25	3:95	4:45	4:60	4:80	5:20
100	6:15	4:70	4:60	4:65	3:65	4:65
200	4:50	4:40	3:65	4:40	4:55	4:70
Dowor						
	20.55	22.1E	24.20	22.1E	41.0E	00.00
20	20.00 10.05	23.13	24.20 50.10	33.10 75.95	01.00	09.90 100.00
50	47.75	47.70 67.05	94·30	01.05	77.20 100.00	100.00
100	00.10	00.05	100.00	100.00	100.00	100.00
200	100.00	100.00	100.00	100.00	100.00	100.00
H test	100.00	100.00	100.00	100.00	100.00	100.00
20	6.20	5.40	5.05	4.30	4.75	6.25
30	7:30	6:00	5:20	5:45	5:25	6:30
50	7:40	6:20	5:10	5:65	5:50	5:70
100	6:80	5:40	4:80	5:30	6:20	5:55
200	6:40	5:20	5:35	5:15	5:30	5:70
¢ test						
20	4:40	7:10	9:95	18:65	48:30	84:25
30	7:00	19:15	33:15	60:40	98:10	100:00
50	9:95	26:15	54:40	79:35	99:95	100:00
100	26:55	77:40	99:00	100:00	100:00	100:00
200	62:25	<u>99:60</u>	100:00	100:00	100:00	100:00

Table 2 : Size and Power of Slope Homogeneity Tests, with Strictly Exogenous Regressors: ${}^{1}A^{2}(2)$; 2 =2 Errors

Notes: See the notes on Table 1. The design is the same as that of Table 1 except "_it \gg IID " $\hat{A}^2(2)$; 2 =2 .

	k	1		211100130		2	k	1
NnT	20 K=	30	20 K=	<u>= 2</u> 30	20 K=	= <u>3</u> 30	- <u>K</u> : 20	= 4 30
SIZE	20	30	20	50	20	30	20	50
Ŝ test								
20	11:40	8:35	16:55	10:80	20:40	13:70	26:50	16:30
30	13:40	11:20	21:25	13:10	25:70	15:70	31:90	17:05
50	15:80	11:60	24:85	15:90	36:45	20:15	43:00	22:45
100	22:45	15:25	35:90	20:90	48:90	26:85	60:90	33:95
200	34:50	20:10	54:55	30:05	72:10	41:95	83:10	50:30
H test								
20	5:60	5:40	6:20	6:45	6:50	5:40	5:45	5:90
30	5:50	6:00	6:45	5:30	6:55	5:95	6:75	6:40
50	5:45	5:75	6:85	6:30	6:75	6:30	7:65	8:15
100	6:90	5:80	7:10	5:60	6:50	5:85	6:10	6:05
200	5:60	5:70	6:20	5:15	5:75	6:70	7:05	6:05
¢ test								
20	3:80	3:20	5:00	4:75	5:20	5:35	5:60	6:05
30	3:55	4:75	5:50	4:70	5:10	5:05	5:00	5:20
50	4:60	4:15	5:55	4:75	5:40	6:05	4:70	5:05
100	4:80	4:35	5:25	5:65	5:15	5:05	5:60	5:20
200	5:05	5:25	4:80	5:50	5:30	5:25	4:70	4:/5
Douvor								
Power								
	75.15	04.15	75.45	00.25	71.40	07.10	62.70	40.40
20	75.15	94.10 00.05	75.05	90.20 02.05	71.40 01.55	07.10	02.70	09.00
50 50	94.20 100.00	90.90 100.00	100.00	93.65 100.00	100.00	92.00 100.00	94.50 100.00	90.70 100.00
100	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
200	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
H test	100.00	100.00	100.00	100.00	100.00	100.00	100100	100.00
20	6:90	8:40	6:40	7:05	6:25	6:90	6:75	5:90
30	5:95	4:55	7:35	5:95	6:45	6:15	6:20	5:80
50	6:30	5:40	6:70	5:85	6:90	6:65	6:35	5:75
100	4:85	5:65	6:00	4:95	6:55	6:75	6:80	6:30
200	6:10	5:10	6:90	5:25	6:00	5:80	5:95	5:65
¢ test								
20	46:35	84:50	38:10	67:30	21:70	52:80	10:40	25:05
30	70:15	94:25	28:50	68:35	26:55	58:15	32:05	73:05
50	100:00	100:00	99:05	100:00	94:85	100:00	75:70	99:90
100	99:65	100:00	98:70	100:00	98:25	100:00	98:45	100:00
200	100:00	100:00	100:00	100:00	100:00	100:00	99:95	100:00

Table 3 : Size and Power of the Slope Homogeneity Tests with Strictly Exogenous Regressors with Digerent Numbers of Covariates (k)

Notes: The DGP is speci...ed as $y_{it} = \circledast_i + \Pr_{k=1}^k x_{it} = 1; 2; ...; N; t = 1; 2; ...; N; t$

			Size			_			Power		
NnT	20	30	50	100	200		20	30	50	100	200
· ·		= اد	= 0:2 for a	all i		-		≪ i ی	IIDU(0:0); 0:4)	
S test											
20	4:60	5:10	5:60	4:35	4:50		13:85	22:55	42:95	82:55	99:75
30	5:50	5:60	4:40	4:80	6:30		20:25	35:25	62:70	96:45	100:00
50	4:50	4:90	4:05	4:60	4:15		24:75	45:30	78:85	99:70	100:00
100	3:55	4:60	4:40	5:50	4:75		41:75	74:90	98:45	100:00	100:00
200	3:30	5:00	4:85	5:00	5:80		62:30	93:85	99:95	100:00	100:00
H tes	t								~~ ~~		
20	38:50	53:40	65:75	73:40	78:00		51:35	75:05	93:80	99:40	100:00
30	45:55	65:25	79:75	88:30	91:45		64:70	89:45	99:00	100:00	100:00
50	62:80	85:25	96:30	98:60	99:50		93:80	99:60	100:00	100:00	100:00
100	89:15	98:85	100:00	100:00	100:00		97:70	99:95	100:00	100:00	100:00
200	99:65	100:00	100:00	100:00	100:00		100:00	100:00	100:00	100:00	100:00
¢ test	t										
20	2:55	2:20	2:80	3:10	2:90		2:40	8:80	25:80	71:75	99:20
30	3:05	2:95	3:15	4:00	3:95		3:70	14:25	43:55	92:55	100:00
50	4:55	4:10	4:05	4:40	3:70		3:75	18:10	59:00	99:30	100:00
100	8:90	5:80	4:65	4:40	4:35		6:50	39:85	93:55	100:00	100:00
200	18:95	8:95	6:45	4:25	4:55		9:25	65:90	99:80	100:00	100:00
			0.4 for							2. 0.4)	
Ê tost		= اد	0.4 101			•		<u>« اد</u>		2, 0.0)	
20	5.70	5.55	6.25	1.70	1.25		16.15	26.10	10.25	Q7·15	00.05
20	5.05	6.20	5.55	4.70	4.20		24.05	20.10 /1./0	47.23 71.00	07.45	77.73 100.00
50	5.75 6·40	6.20	5.33 5.10	5.80	0.30 4·75		24.05	53.40	85.95	90.33 99.85	100.00
100	5.45	6.10	5.60	6.00	5.25		51.00	82·75	00.75	100.00	100.00
200	6.60	6.40	6.80	5.55	5.60		85.80	98·70	100.00	100.00	100.00
H test	t 0.00	0.40	0.00	0.00	5.00		00.00	70.70	100.00	100.00	100.00
20	73.25	87.20	92.80	94.65	96.20		83.45	95.55	99.65	100.00	100.00
30	90.20	96·45	99·15	99.40	99.70		96·75	99·65	100.00	100.00	100.00
50	99·15	99·95	100.00	100.00	100.00		99.95	100.00	100.00	100.00	100.00
100	100.00	100.00	100.00	100.00	100.00		100.00	100.00	100.00	100.00	100.00
200	100.00	100.00	100.00	100.00	100.00		100.00	100.00	100.00	100.00	100.00
t toot	+	100.00	100.00	100.00	100.00		100.00	100.00	100.00	100.00	100.00
20	2∙80	2.20	3.00	3.20	3.12		3.70	11.05	31.75	78.75	99·85
20	2.00	2.20	3.00	3.20 2.85	<u>⊿</u> .70		J.70 <u></u> ∆∙60	18.40	53.75	96.60	100.00
50	2.70	2.05	3.40 2.05	J.55 ∐.55	- 1 .70 2∙∕10		-7.00 6·25	25.15	60.35	90.00 90.70	100.00
100	6.35	4.65	4·15	4.05	<u></u> 4.70		10.35	54·00	97.60	100.00	100.00
200	12.50	4.00	5.45	.05 ∦.05			18.15	81·20	00·05	100.00	100.00
200	12:50	4.05 6:30	5:65	4:05	4.70 5:00		18:45	81:30	97.00 99:95	100:00	100:00

Table 4 : Size and Power of the Slope Homogeneity Tests for Heteroskedastic AR(1) Speci...cations

Notes: See notes to Table 1. Ŝ test, ¢ test; and H test statistics are de...ned in (2.10), (4.6), and (5.1), respectively. The DGP is speci...ed as $y_{it} = (1_{i} \ _{i})^{\circledast}_{i} + _{i}y_{it_{1}} + _{it_{1}}t = _{i} 49; ...; 0; ...; T, i = 1;2; ...; N, where; <math>\circledast_{i} \gg N(1;1); _{_{i}i}$ are as speci...ed in the table; $"_{it} \gg IIDN \ 0; \#_{i}^{2}$ with $\#_{i}^{2} \gg IIDA^{2}(2)=2$. $\circledast_{i}, _{_{i}i}$, and $\#_{i}^{2}$ are ...xed for replications. $y_{i;i} 49 = \circledast_{i}$, and the ...rst 49 observations are discarded. We reject the null hypothesis when we obtain negative (H test) statistics (due to negative variance estimates, ψ_{H}).

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			Size					Power		
NnT	20	30	50	100	200	20	30	50	100	200
		= اد	= 0:6 for a	all i			_{ه ا د}	11DU(0:4	4; 0:8)	
Ŝ test										
20	7:50	7:60	7:10	5:40	4:85	21:90	35:50	62:00	95:10	99:95
30	9:15	8:40	6:65	5:45	6:45	34:10	55:40	85:55	99:90	100:00
50	9:55	9:55	7:65	6:15	5:15	45:70	69:60	94:70	100:00	100:00
100	11:00	10:50	8:00	6:70	6:50	73:65	95:10	100:00	100:00	100:00
200	15:75	13:20	10:60	7:10	7:60	93:10	99:65	100:00	100:00	100:00
H tes	t									
20	91:45	97:00	98:50	98:95	99:35	96:45	99:50	100:00	100:00	100:00
30	98:95	99:70	100:00	100:00	100:00	99:90	100:00	100:00	100:00	100:00
50	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00
100	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00
200	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00
¢ test	t									
20	2:40	2:35	4:15	3:05	3:05	5:95	16:00	44:60	90:50	99:95
30	2:35	3:10	3:60	3:40	5:10	8:75	29:40	72:90	99:40	100:00
50	2:65	3:75	3:95	4:15	4:40	12:15	40:30	87:10	100:00	100:00
100	4:35	3:65	3:80	4:40	4:90	25:30	77:30	99:90	100:00	100:00
200	6:15	4:00	4:80	3:90	4:70	44:35	96:20	100:00	100:00	100:00
· ·		= اد	= 0:8 for	alli			_{د اد}	11DU(0:0	5; 1:0)	
S test	•									
20	13:40	11:45	10:05	6:35	5:50	34:55	54:20	84:45	99:95	100:00
30	16:10	14:25	11:35	7:35	8:20	54:75	78:65	98:10	100:00	100:00
50	20:75	17:00	12:40	9:25	7:05	73:15	94:05	100:00	100:00	100:00
100	29:55	24:40	17:90	10:50	9:20	93:80	99:90	100:00	100:00	100:00
200	46:30	35:30	25:45	13:70	11:45	99:85	100:00	100:00	100:00	100:00
H tes	t									
20	96:30	99:15	99:40	99:85	99:90	98:50	100:00	100:00	100:00	100:00
30	99:70	100:00	100:00	100:00	100:00	99:95	100:00	100:00	100:00	100:00
50	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00
100	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00
200	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00	100:00
¢ test	t									
20	3:05	3:70	4:95	3:90	3:60	11:70	32:55	72:35	99:85	100:00
30	3:45	4:45	4:45	4:00	4:90	21:55	56:90	95:20	100:00	100:00
50	2:95	5:35	4:35	4:75	4:85	36:35	78:95	99:40	100:00	100:00
100	4:35	5:70	5:55	4:75	5:80	64:95	97:90	100:00	100:00	100:00
200	4:70	7:05	8:30	5:95	6:25	89:90	100:00	100:00	100:00	100:00

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			Size						Power		
NnT	20	30	50	100	200	•	20	30	50	100	200
		= اد	= 0:9 for a	all i		,i ≫ IIDU(0:0; 1:0)					
Ŝ test	-					•					
20	20:40	18:20	15:30	9:50	7:70		89:15	99:55	100:00	100:00	100:00
30	27:30	22:10	18:40	10:65	9:40		99:30	100:00	100:00	100:00	100:00
50	37:80	30:35	22:60	15:20	10:00		99:95	100:00	100:00	100:00	100:00
100	56:40	47:20	36:50	21:30	14:35		100:00	100:00	100:00	100:00	100:00
200	79:40	70:50	54:65	33:10	19:90		100:00	100:00	100:00	100:00	100:00
H tes	t										
20	97:40	99:05	99:80	100:00	99:95		99:80	100:00	100:00	100:00	100:00
30	99:80	100:00	100:00	100:00	100:00		100:00	100:00	100:00	100:00	100:00
50	100:00	100:00	100:00	100:00	100:00		100:00	100:00	100:00	100:00	100:00
100	100:00	100:00	100:00	100:00	100:00		100:00	100:00	100:00	100:00	100:00
200	100:00	100:00	100:00	100:00	100:00		100:00	100:00	100:00	100:00	100:00
¢ tes	t										
20	4:85	6:10	6:75	5:20	4:60		69:00	97:55	100:00	100:00	100:00
30	6:00	7:55	8:00	5:95	6:25		94:70	100:00	100:00	100:00	100:00
50	8:15	9:70	10:05	8:10	5:95		99:65	100:00	100:00	100:00	100:00
100	13:85	15:90	14:95	11:30	8:95		100:00	100:00	100:00	100:00	100:00
200	24:00	26:35	25:05	16:25	10:80		100:00	100:00	100:00	100:00	100:00

Table 5 : Size and Power of the Slope Homogeneity Tests for Heteroskedastic AR(2) Speci...cations

	Size							Power		
NnT	20	30	50	100	200	20	30	50	100	200
	20		- 0.6 for	2001 2011 i	200	20			100	200
Ĉ toot		ا ا د	- 0.0 101				<i>س</i> ا1 د		4,0.0)	
S les l	14 (0	10.00	10.40	(00	(50	20.45	20 (0	(0.70	0/ 00	100.00
20	14:60	13:30	10:40	6:80	6:50	30:45	39:60	63:70	96:90	100:00
30	18:65	16:20	11:05	/:00	6:50	46:15	59:25	88:80	100:00	100:00
50	25:75	19:85	13:25	8:75	6:15	60:50	78:50	97:75	100:00	100:00
100	37:05	26:95	19:10	12:05	9:25	85:05	97:20	99:95	100:00	100:00
200	56:50	42:45	26:90	15:50	10:05	97:60	100:00	100:00	100:00	100:00
H tes	t									
20	90:65	96:25	98:35	98:45	97:60	95:00	98:60	96:80	98:05	100:00
30	98:45	99 :55	99:50	99:35	99:00	99:60	99:25	97:90	99:75	100:00
50	100:00	100:00	99:90	99:80	99:75	99:95	99:55	99:20	100:00	100:00
100	100:00	100:00	100:00	99:95	100:00	100:00	99:80	99:45	100:00	100:00
200	100:00	100:00	100:00	100:00	100:00	100:00	100:00	99:80	100:00	100:00
¢ tes	t									
20	3:10	3:05	4:10	4:00	4:80	4:70	12:50	38:00	92:30	100:00
30	2:95	3:55	3:95	3:65	4:45	7:25	24:05	71:30	99:80	100:00
50	2:20	3:65	3:90	5:05	5:15	13:30	38:70	88:90	100:00	100:00
100	2:65	3:80	5:10	5:40	5:90	25:20	74:90	99:85	100:00	100:00
200	3:40	4:55	5:75	5:95	4:65	43:55	96:50	100:00	100:00	100:00

Notes: See notes to Table 1 and 4. The DGP is $y_{it} = (1_{i} \downarrow_{i1} \downarrow_{i2})^{(i)} + \downarrow_{i1} y_{it_{i1}} + \downarrow_{i2} y_{it_{i2}} + \downarrow_{it}, t = j_{i1} 49; \dots; 0; \dots; T, i = 1; \dots; N, \downarrow_{i1}$ is as specimed in the table, $\downarrow_{2} = 0:2$. The …rst 48 observations are discarded.

		Size			Power	
NnT	20	30	50	20	30	50
	.i =	0:2 for a	all i	.i »	IDU(0:	0;0:4)
Stand	ard No	ormal				
20	1:60	1:65	2:60	3:50	8:45	26:85
30	3:30	3:40	2:75	4:05	12:90	42:85
50	5:20	3:60	4:35	3:95	17:35	58:35
100	9:20	4:90	4:65	7:00	40:25	92:30
200	19:25	10:75	6:75	9:55	67:75	99:80
Boots	strap					
20	4:30	4:45	4:80	5:40	11:10	30:60
30	4:90	5:05	4:45	5:60	16:25	47:40
50	5:05	5:05	5:45	4:45	18:70	61:95
100	5:20	4:40	5:00	4:55	38:35	92:60
200	6:15	5:35	5:30	2:85	57:20	99:80
Bias-(Correct	ed Boo	ntstran			
20	4.25	4.55	4.70	5.20	11.30	30.75
30	5:00	5:20	4:70	5:90	16:35	47:35
50	5.40	5.30	5.75	4.85	18.75	61.55
100	5.75	4.25	5.10	5.00	38.90	92.50
200	7:30	5:50	5:45	2:80	58:00	99:80
	. –	0.1 for	all i			2.0.6)
Stand	ard No	ormal		/ // /	100(0.	2, 0.0)
20	2.45	2.65	2.75	3.60	10.40	29.05
30	2:35	3:05	3:15	4:85	18:75	52:85
50	4.50	3.90	3.70	6.10	23.15	69.55
100	7:90	5:85	4:15	11:60	52:50	97:60
200	12:75	6:95	5:90	18:85	82:00	99:95
Boots	strap					
20	5.40	5.20	4.62	6.35	13.95	33.90
30	<i>1</i> .40 <i>1</i> .25	5.30	4.05 <u>1</u> .05	6.50	22.20	56.70
50	5.25	5.35	5.05	0.00 7·15	25.50	72.25
100	5.65	5.65	5.00	9.60	51.00	97.80
200	5:20	4:80	5:35	9:90	78:30	99:95
Dias (Correct	od Doo	totror			
DI02-0				6.15	12.0F	24.10
20	00.0	0:00	4.9U	0:10	10:00	34:1U
30	4:70	5:35 E-00	4:/5	0:/5	22:20	30:4U
5U 100	5:4U	03:0U	4:05	10.05	20:70	12:15
200	0:30	0:1U 5:20	5:05	10:25	53:20 70:20	90.0E
200	0:00	5:30	0.90	11:05	79:ZU	77:70

Table 6 : Size and Power of the Bootstrap Test of Slope Homogeneity for Heteroskedastic AR(1) Speci...cations

Notes: See the notes to Table 4. 499 bootstrap samples are generated, and rejection frequencies are based on 2,000 replications. "Bootstrap" is based on the bootstrap samples generated using \tilde{J}_{WFE} . The "Bias-Corrected Bootstrap" is based on the bootstrap samples generated using the bias-corrected estimator, \tilde{J}_{WFE} . For further details see Section 4.2.

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		Size			Power			
NnT	20	30	50	20	30	50		
	$_{i} = 0.6$ for all i			i »	i » IIDU(0:4;0:8)			
Standard Normal								
20	1:40	2:75	3:85	5:40	15:55	43:75		
30	2:60	3:80	2:55	7:50	30:50	73:65		
50	2:45	3:55	3:35	11:30	40:45	87:50		
100	4:25	3:55	4:15	28:00	78:50	99:80		
200	5:75	3:65	4:30	45:45	96:75	100:00		
Bootstrap								
20	4:25	6:05	5:20	8:70	19:85	48:15		
30	4:85	5:70	3:70	10:40	34:65	76:40		
50	4:30	5:40	4:95	14:25	45:80	89:15		
100	4:50	4:60	4:90	29:75	80:50	99:85		
200	4:30	4:30	4:95	40:80	96:80	100:00		
Rias-	Correc	tod R	ootstra	n				
20	1.25		5.25	ο.ου Α	10.40	18.05		
20	4.35	5.30	2.25	10.00	25.25	76.00		
50	4.70	5.20	1.05	14.85	15.80	20.55		
100	4.40 5.50	5.35	4.05	21.05	40.00 80.80	09.00		
200	5.50	J.2J 1.15	4.7J 5·20	15·10	97.05	100.00		
200	0.00	7.70	0.20	40.40	77.00	100.00		
	= ا د	0:8 for	all i	, i » IIDU(0:6;1:0)				
Stand	lard N	ormal						
20	2:40	3:80	4:80	12:60	31:05	71:85		
30	2:95	3:85	5:45	22:05	55:10	95:75		
50	3:20	5:25	5:25	36:90	76:70	99:70		
100	4:65	5:75	5:90	64:90	98:20	100:00		
200	4:65	7:50	8:25	90:55	100:00	100:00		
Bootstran								
20	5:20	5:65	5:70	17:10	35:00	73:70		
30	4:70	5:15	6:25	26:15	58:05	95:70		
50	4:70	6:40	5:60	40:05	75:25	99:70		
100	6:40	6:50	5:75	69:70	98:20	100:00		
200	6:70	8:60	7:55	92:25	100:00	100:00		
Disc Connected Destates								
20			5.20	15.50	21.15	72.25		
20	1.20		1 711	10.00	34.13	13.20		
20	4:50	0.10 1.4 E	5.20	22.0E	55.25	05.20		
30	4:50 4:25	4:65	5:65	23:85	55:35 71:15	95:30		
30 50	4:50 4:25 4:20 5:55	4:65 5:50	5:65 5:25	23:85 32:95 63:10	55:35 71:15 97:60	95:30 99:45		

(Continued)

Size				Power			
NnT	20	30	50	20	30	50	
	$_{\rm al} = 0.9$ for all i			,i×	_{,i} » IIDU(0:0;1:0)		
Stand	lard No	ormal					
20	5:30	6:20	7:60	68:35	97:95	100:00	
30	7:25	7:35	9:35	94:85	99:95	100:00	
50	7:90	9:25	8:95	99:35	100:00	100:00	
100	12:55	15:80	15:45	100:00	100:00	100:00	
200	21:30	27:65	25:40	100:00	100:00	100:00	
Bootstrap							
20	6:00	6:10	7:50	74:15	98:50	100:00	
30	7:95	6:95	7:85	96:05	99:95	100:00	
50	8:45	7:30	6:55	99:60	100:00	100:00	
100	11:95	9:95	8:50	100:00	100:00	100:00	
200	18:35	16:25	10:55	100:00	100:00	100:00	
Bias-Corrected Bootstrap							
20	4:45	4:70	6:25	74:20	98:60	100:00	
30	5:20	4:50	6:05	96:30	99:95	100:00	
50	4:45	3:60	5:35	99:60	100:00	100:00	
100	5:05	4:80	4:95	100:00	100:00	100:00	
200	4:50	5:75	5:65	100:00	100:00	100:00	

		Pooled Sample	High School Dropout	High School Graduate	College Graduate
		e = 0	e = 1	e = 2	e = 3
N		1;031	249	531	251
Average T _i		18:39	18:36	18:22	18:79
Total Observations		18; 961	4; 572	9;673	4;716
Tests for	Slope Homogeneity				
¢ test	Statistic	25:59	7:20	13:65	18:32
	Normal approximation p-value	[0:0000]	[0:0000]	[0:0000]	[0:0000]
	Blas-corrected bootstrap p-value	[0:0000]	[0:0000]	[0:0000]	[0:0000]
Autoregressive Coe¢cient ()					
FE Est	imates (͡٫FE)	0:4841 (0:0065)	0:4056 (0:0147)	0:4497 (0:0095)	0:5538 (0:0106)
WFE E	stimates (_{JWFE})	0:5429	0:4246	0:5169	0:6002
		(0.0000)	(0.0100)	(0.0000)	(0.0070)
Bias-Corrected WFE (^{°, WFF})		0:6504	0:5188	0:6192	0:7214
		(0:0055)	(0:0126)	(0:0080)	(0:0101)

Table 7: Slope Homogeneity Tests and Alternative Estimates of the Autoregressive Coe¢cient of the Real Earnings Equations

Notes: Noting PSID data we used are unbalanced, FE estimator, and WFE estimator are de...ned by (3.23), and (3.22) in Remark 5, respectively, and their associated standard errors (shown in round brackets) are based on $\hat{V} \stackrel{\wedge}{}_{sFE} = \Re^2 \frac{P_N}{i=1} y_{i;i=1}^0 M_{zi} y_{i;i=1}^{i=1}$, where

$$%^{2} = (T | N | 1)^{i} \frac{3}{y_{i}} \frac{3}{FE} y_{i;i} \frac{1}{M_{i}} M_{i} \frac{3}{FE} y_{i;i} \frac$$

 $T = \frac{P_{i=1}}{P_{i=1}} T_{i}, \text{ and } \hat{V}_{3} W F E = \frac{{}^{3}P_{i=1} \frac{3}{4} i^{2} y_{i;i}^{0} M_{i;i} y_{i;i}^{-1}}{}^{1} M_{i;i} y_{i;i}^{-1} \frac{1}{2} .$

Bias corrected estimates are based on $^{\circ}_{WFE} = _{\circ}_{WFE} + (T=N) + _{\circ}_{WFE}$ and $\hat{V} ^{\circ}_{WFE} = T + 1 + _{i} + _{i}$